


Binding, Scope & Storage Allocation

CS2210
Lecture 9


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Reading

- Chapter 7 except 7.9
- Muchnick: 1-3
 - Just skim, should be nothing new, just different notation


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Binding, Scope & Storage

- 1) Converted input into tokens w/ attributes
- 2) Parsed token sequence and created abstract syntax tree using semantic actions
- 3) Typechecked abstract syntax tree
- 4) To generate (intermediate) code
 - 1) Have to map names to storage locations
 - 2) Have to generate code to access data at run time


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Binding

- Binding association of attributes with actual values
 - Eg. Storage location of variable x with its location in memory (global, local, heap)
- The time when each of these occurs in a program is the **binding time** of the attribute
 - **Static binding**: occurs before runtime and does not change during program execution
 - **Dynamic binding**: occurs during runtime or changes during runtime


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Binding

- **Name**:
 - Occurs when program is written (chosen by programmer) and for most languages will not change: static
- **Address and Lifetime**:
 - A memory location for a variable must be **allocated** and **deallocated** at some point in a program
 - The lifetime is the period between the allocation and deallocation of the memory location for that variable


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Lifetimes

- **Static**: bound to same memory cell for entire program
 - Ex: static C++ variables
- **Stack-dynamic**: bound and unbound based on runtime stack
 - Ex: Pascal, C++, Ada subprogram variables
- **Explicit heap-dynamic**: nameless cells that can only be accessed using other variables (pointers / references)
 - Allocated explicitly by the programmer
 - Ex: result of new in C++ or Java


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Lifetimes (2)

- **Implicit heap-dynamic variables**
 - Binding of all attributes (except name) changed upon each assignment
 - Much overhead to maintain all of the dynamic information
 - Used in Algol 68 and APL
 - Not used in most newer languages except some functional languages like ML
- **Value**
 - Dynamic by the nature of a variable – can change during run-time


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Binding & Types

- **Type**
 - **Dynamic Binding**
 - Type associated with a variable is determined at run-time
 - A single variable could have many different types at different points in a program
 - **Static Binding**
 - Type associated with a variable is determined at compile-time (based on var. declaration)
 - Once declared, type of a variable does not change


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Scope

- **Scope = determines what names are visible at program points**
 - Scope ~ where
 - Lifetime ~ when
- **Static scope**
 - determined at compile-time
- **Dynamic scope**
 - determined at run-time
- **Choice determines**
 - What non-locals are visible
 - How are visible locals accessed


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Static Scope

- Most modern languages use static scope
 - If variable is not locally declared, proceed out to the “textual parent” (static parent) of the block/subprogram until the declaration is found
 - Fairly clear to programmer – can look at code to see scope


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Dynamic Scope

- Non-local variables are accessed via calls on the run-time stack (going from top to bottom until declaration is found)
 - A non-local reference could be declared in different blocks in different runs
 - Used in APL, SNOBOL4 and through **local** variables in Perl


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Dynamic Scope (cont.)

- Flexible but very tricky
 - Difficult for programmer to anticipate different definitions of non-local variables
 - Type-checking must be dynamic, since types of non-locals are not known until run-time
 - More expensive to implement


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Scope, Lifetime and Referencing Environments

- More often they are not “the same”
 - Lifetime of stack-dynamic variables continues when a subsequent function is called, whereas scope does not include the body of the subsequent function
 - Lifetime of heap-dynamic variables continues even if they are not accessible at all


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Scope, Lifetime and Referencing Environments

- Referencing Environment
 - Given a statement in a program, what variables are visible there?
 - Depends on the type of scoping used
 - Once we know the scope rules, we can always figure this out
 - From code if static scoping is used
 - From call chains (at run-time) if dynamic scoping is used

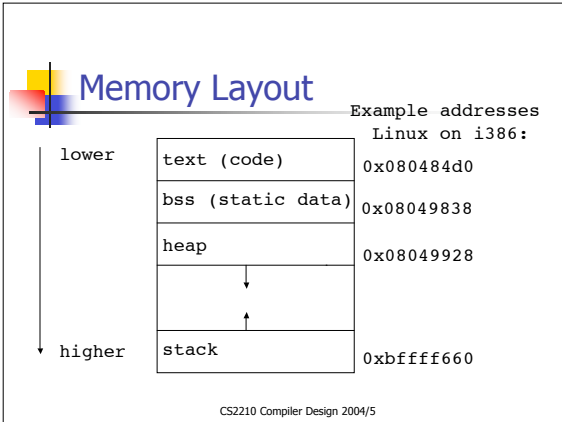
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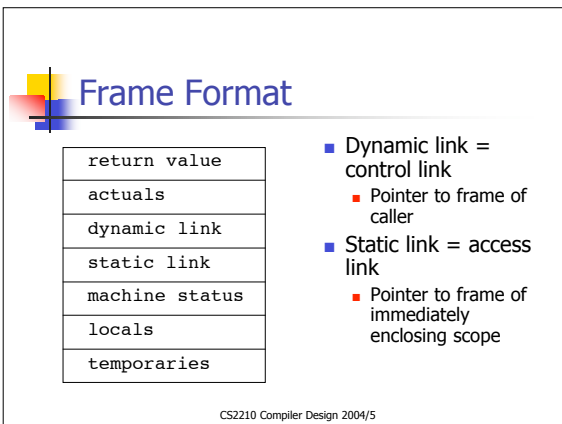
Procedure Lifetimes


- **Activation**
 - Execution of a procedure
 - Active until procedure returns
 - Multiple activations of same procedure possible (recursion)

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- ## Activation Records
- Data structure containing information needed by a single execution of a procedure - aka (**stack**) **frame**
 - Contained fields depend on the language and calling convention of the target architecture
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Alpha Processor Format

[fixed temporary locations]	0 (from SP)
register save area	PDESC_RPD_RSA_OFFSET (from SP)
[fixed temporary locations]	
[argument home area]	
[arguments passed in memory]	PDESC_RPD_FRAME_SIZE (from SP)


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Alpha Calling Convention

- Most arguments passed in registers
 - r16 ... r21 on the Alpha
- Return value passed in return register
 - r0 on the Alpha, f0 for floating point values
- Frame pointer register
 - Used if frame size can vary at run time
 - \$15 on the Alpha
- Return address register (address of instruction following call instruction)
 - \$26 on the Alpha

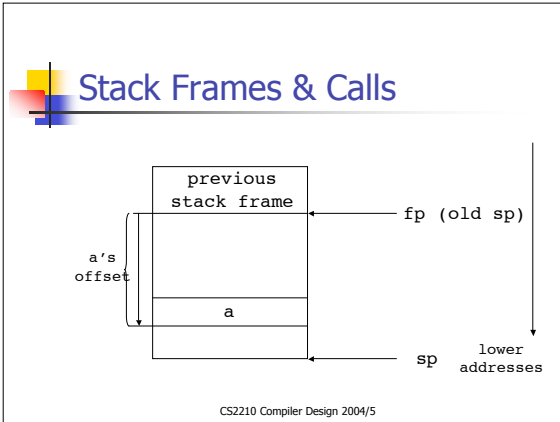
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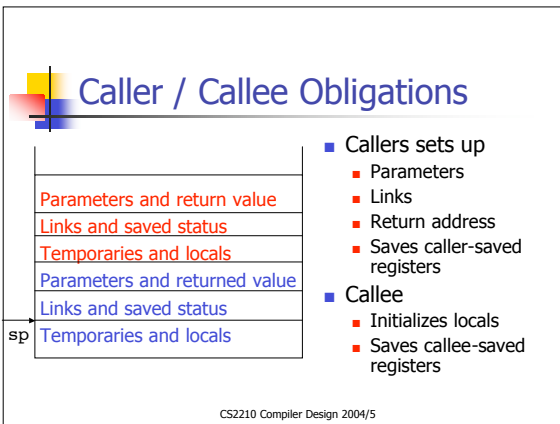


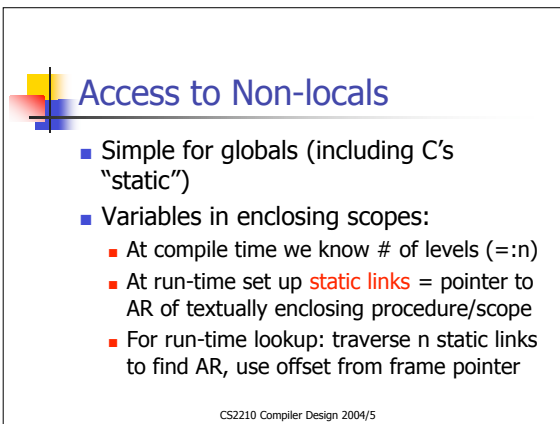
MIPS Calling Convention

- \$a0 ... \$a3 argument registers
- \$t0 ... \$t9 are temporary registers (caller-saved)
- \$ra for return address

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How do we set up the static link?

p calls q, nesting depth n_p and n_q :

- $n_p < n_q$:
 - q must be declared within p
 - Static link points to immediate caller
- $n_p \geq n_q$:
 - Traverse $n_p - n_q$ links to find AR of procedure at level n_q , then use that AR's static link,
 - i.e., we find the most recent AR of q's immediate enclosing by following $n_p - n_q + 1$ static links

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```

program sort(input, output);
var a : array [0..9] of integer;
    x : integer;

procedure readarray;
var i : integer;
begin (read array a) end (readarray);

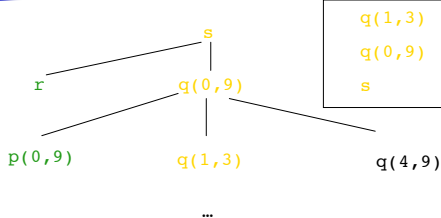
procedure exchange(i, j : integer);
begin
  x := a[i]; a[i] := a[j]; a[j] := x
end (exchange);

procedure quicksort(m,n : integer);
var k, v : integers;
function partition(y,z : integer) : integer;
var i, j : integer;
begin
  (stuff)
  exchange(i, j);
end (partition);
begin
  k = partition(m,n); quicksort(m+1,k);
  quicksort(k+1,n);
end; { quicksort }


begin
  readarray; quicksort(0,9) {sort}
end.
{sort}
    
```

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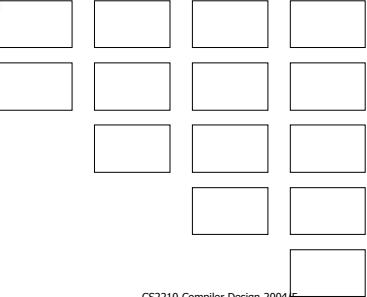
Activation Tree / Stack




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Example:




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Static Link Evaluation

- Good
 - Little work at call
 - Only add one static link
 - Access to locals remains fast
- Bad
 - Expensive access to non-locals if many levels are involved

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Displays

- Alternative to static links
 - Maintain a single array that has pointers to all relevant activation records
 - Have to update array at every call & return
- Pros & Cons
 - Fast access to non-locals
 - Higher maintenance cost
 - Pays off for high nesting levels & many non-local accesses

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Dynamic Scoping

- Two implementation methods
 - Deep access
 - Shallow access
- Important: both implement the same semantic model
 - Deep and shallow binding are different concepts
 - Refer to the referencing environment of procedural parameters:
 - Deep binding = environment of definition of passed proc.
 - Shallow binding = environment of the calling proc.

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Referencing environment

```

Procedure sub1;
var x:integer;
procedure sub2;
begin
  write('x = ', x);
end;
Procedure sub3;
var x: integer;
begin;
  x := 3;
  sub4(sub2);
end;
Procedure sub4(subx);
var x: integer;
begin
  x := 4;
  subx;
end;
Begin
  x := 1;
  sub3;
End;

```

- 3 binding options
 - Shallow
 - Where proc is CALLED (dynamic)
 - Deep
 - Where proc is DEFINED (static)
 - Ad hoc
 - Where proc is PASSED

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Deep Access

- Use dynamic link for name lookup
 - May traverse many links, hence "deep access"
 - Have to store variables with their names
 - Can't use offset method because # of traversed links unknown at compile time
 - More expensive than static scoping

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Shallow access

- Analogue of displays in the static scope world
- Use a stack for each variable, e.g.:

P1 P2	P3 P3	P4 P1 P2	P1 P2	P1
Var: a	b	c	d	e

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Parameter Passing


- Three semantic classes (semantic models) of parameters
 - IN: pass value to subprogram
 - OUT: pass value back to caller
 - INOUT: pass value in and back
- Implementation alternatives
 - Copy value
 - Pass an access path (e.g. a pointer)

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Parameter Passing Methods

- Pass-by-Value
- Pass-by-Reference
- Pass-by-Result
- Pass-by-Value-Result (copy-restore)
- Pass-by-Name


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Pass-by-value

- Copy actual into formal
 - Default in many imperative languages
 - Only kind used in C and Java
 - Used for **IN** parameter passing
 - Actual can typically be arbitrary expression including constant & variable


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Pass-by-value cont.

- Advantage
 - Cannot modify actuals
 - So IN is automatically enforced
- Disadvantage
 - Copying of large objects is expensive
 - Don't want to copy whole array each call!
- Implementation
 - Formal allocated on stack like a local variable
 - Value initialized with actual
 - Optimization sometimes possible: keep only in register


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Pass-by-result

- Used for OUT parameters
 - No value transmitted to subprogram
 - Actual **MUST** be variable (more precisely lvalue)
 - `foo(x)` and `foo(a[1])` are fine but not `foo(3)` or `foo(x * y)`

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Pass-by-result gotchas


```

procedure foo(out int x, out int
y) {
  g := 4;
  x := 42;
  y := 0;
}
main() {
  b: array[1..10] of integer;
  g: integer;
  g = 0;
  call to foo:
}

```

- foo(a,a); print(a)
what is printed?
- foo(b[g], ...): which
element is modified?


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Pass-by-value-result

- Implementation model for in-out parameters
- Simply a combination of pass by value and pass by result
 - Same advantages & disadvantages
 - Actual must be a lvalue

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Pass-by-reference

- Also implements IN-OUT
 - Pass an access path, no copy is performed
- Advantages:
 - Efficient, no copying, no extra space
- Disadvantages
 - Parameter access usually slower (via indirection)
 - If only IN is required, may change value inadvertently
 - Creates aliases

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Pass-by-reference aliases

```

int g;
void foo(int& x) {
  x = 1;
}
foo(g);

```

- g and x are aliased

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Pass-by-name

- Textual substitution of argument in subprogram
 - Used in Algol for in-out parameters
 - evaluated at each reference to formal parameter in subprogram
 - Subprogram can change values of variables used in argument expression
 - Programmer must rename variables in subprogram in case of name clashes
 - Evaluation uses reference environment of caller

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Jensen's device


```

real procedure sigma(x, i, n);
  value n;
  real x; integer i, n;
begin
  real s;
  s := 0;
  for i := 1 step 1 until n do
    s := s + x;
  sigma := s;
end

```

What does sigma(a(i), i, 10) do?


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Design Issues

- Typechecking
 - Are procedural parameters included?
 - May not be possible in independent compilation
 - Type-loophole in original Pascal: was not checked, but later procedure type required in formal declaration


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Pass-by-name Safety Problem

```
procedure swap(a, b);
integer a,b,temp;
begin
  temp := a;
  a := b;
  b := temp;
end;
swap(x,y):
swap(i, x(i))
```

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Call-by-name Implementation

- Variables & constants easy
 - Reference & copy
- Expressions are harder
 - Have to use parameterless procedures aka. **Thunks**

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Think Example

```

real procedure sigma(x, i, n);
  value n;
  real x; integer i, n;
begin
  real s;
  s := 0;
  for i := 1 step 1 until n do
    s := s + x;
  sigma := s;
end

sigma(a(i)*b(i), i, 10)
function iThink() :IntVarAddress;
begin
  iThink := ADDRESS(I)
end;
function xiThink()
:RealVarAddress;
var expl;
begin
  expl := a(I)*b(I);
  xiThink := ADDRESS(expl);
end;

```

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Think Evaluation

```

real procedure sigma(x, i, n);
  value n;
  real x; integer i, n;
begin
  real s;
  s := 0;
  for i := 1 step 1 until n do
    s := s + x;
  sigma := s;
end
function iThink() :IntVarAddress;
begin
  iThink := ADDRESS(I)
end;
function xiThink() :RealVarAddress;
var expl;
begin
  expl := a(I)*b(I);
  xiThink := ADDRESS(expl);
end;

real procedure sigma(xiThink(),
  iThink(), 10);
begin
  real s;
  s := 0;
  for iThink()^ := 1 step 1
  until n do
    s := s + xiThink()^;
  sigma := s;
end

```

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Procedures as Parameters

- In some languages procedures are **first-class citizens**, i.e., they can be assigned to variables, passed as arguments like any other data types
- Even C, C++, Pascal have some (limited) support for procedural parameters
- Major use: can write more general procedures, e.g. standard library in C:

```

qsort(void* base, size_t nmem, size_t
size, int(*compar)(const void*, const
void*));

```

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Design Issues

- Typechecking
 - Are procedural parameters included?
 - May not be possible in independent compilation
 - Type-loophole in original Pascal: was not checked, but later procedure type required in formal declaration

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Referencing environment

```

Procedure sub1;
var x: integer;
procedure sub2;
begin
  write('x = ', x);
end;
Procedure sub3;
var x: integer;
begin;
  x := 3;
  sub4(sub2);
end;
Procedure sub4(subx);
var x: integer;
begin
  x := 4;
  subx;
end;
Begin
  x := 1;
  sub3;
End;

```

- 3 binding options
 - Shallow (aka activation environment)
 - Where proc is CALLED (dynamic)
 - Deep (aka lexical environment)
 - Where proc is DEFINED (static)
 - Ad hoc (aka passing environment)
 - Where proc is PASSED


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Procedures as parameters

- How do we implement static scope rules?
 - = how do we set up the static link?

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```

program param(input, output);

procedure b(function h(n : integer):integer);
begin writeln(h(2)) end {b};

procedure c;
var m : integer;


    function f(n : integer) : integer;
begin f := m + n end {f};

begin m := 0; b(f) end {c};

begin
    c
end.

```


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Solution: pass static link:

param
c
b

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Another Example

```

program fun;
procedure p1;
begin {...} end; {p1}

procedure p2(procedure x);
var n : integer;


    procedure p3;
begin n = 0; end; {p3}

begin x; p2(p3); end; {p2}

begin {main} p2(p1) end. {main}

```

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Activation records

fun	
p2	
p1	p2
	p3

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