

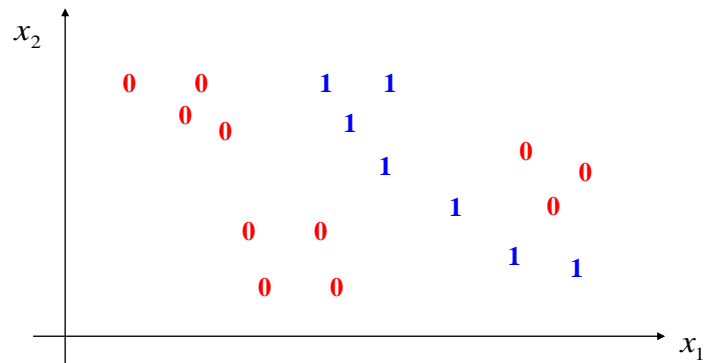
CS 2750 Machine Learning Lecture 12b

Decision trees

Milos Hauskrecht
milos@cs.pitt.edu
5329 Sennott Square

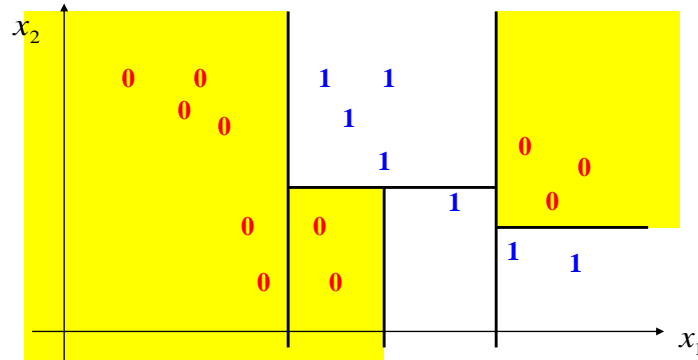
Decision tree classification

- An alternative approach to classification:
 - Partition the input space to regions
 - Regress or classify independently in every region



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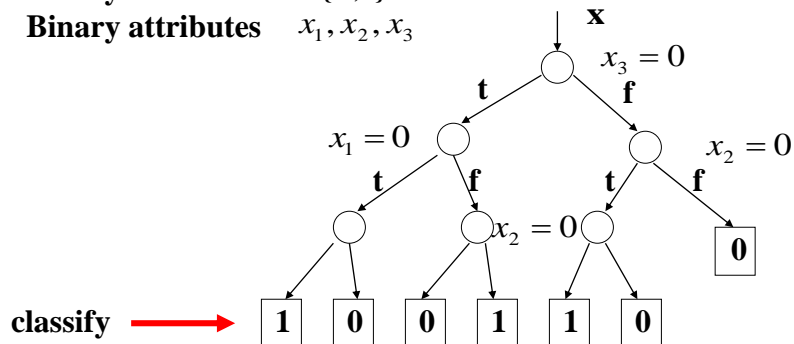
Decision tree model:

- Split recursively the input space \mathbf{x} using simple conditions on x_i
- Classify at the bottom of the tree

Example:

Binary classification $\{0,1\}$

Binary attributes x_1, x_2, x_3



Decision trees

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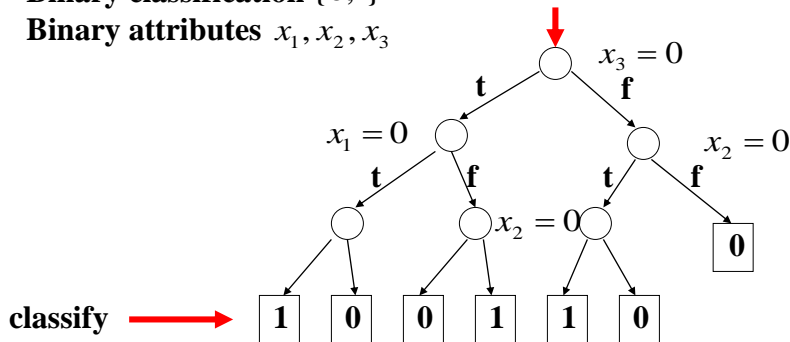
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Decision trees

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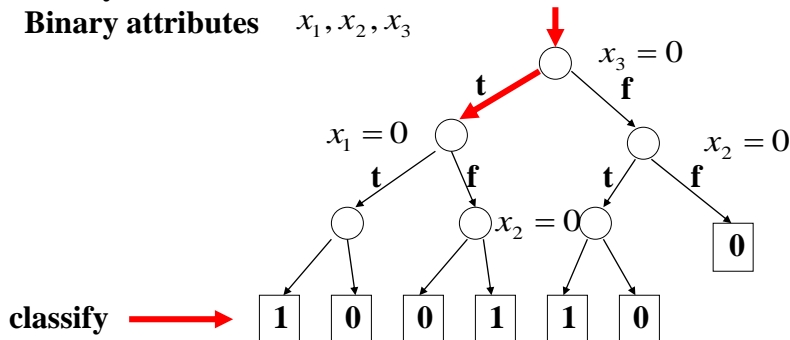
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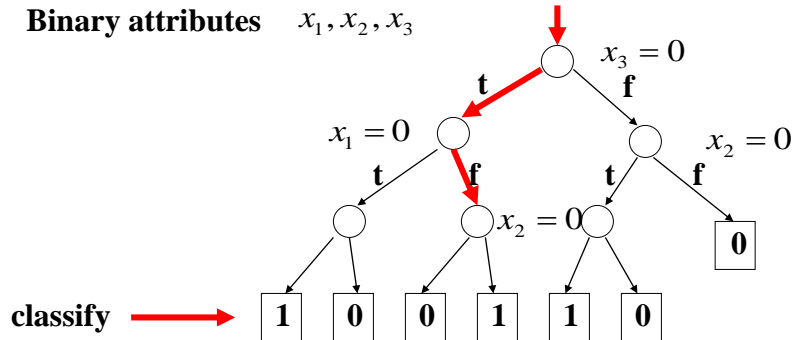
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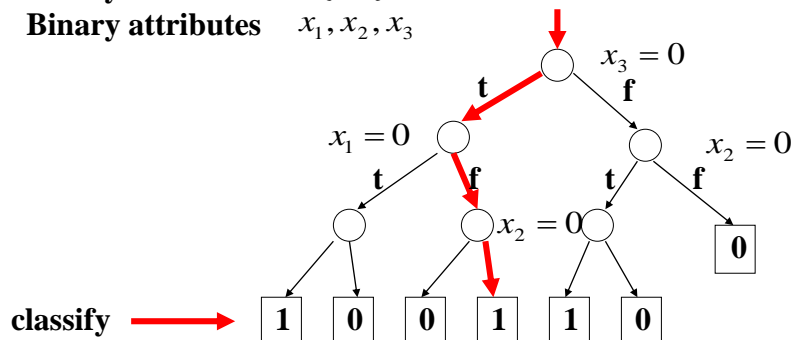
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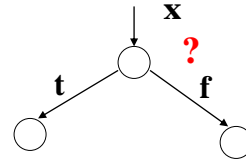


Learning decision trees

How to construct /learn the decision tree?

- **Top-bottom algorithm:**

- Find the best split condition (quantified based on the **impurity measure**)
- Stops when no improvement possible



- **Impurity measure $I(D)$:**

- measures the degree of mixing of the two classes in the subset of the training data D
- Worst (maximum impurity) when # of 0s and 1s is the same

- Splits: **finite or continuous value attributes**

Continuous value attributes conditions: $x_3 \leq 0.5$

Impurity measure

Let $|D|$ - Total number of data instances in D

$|D_i|$ - Number of data entries classified as i

$p_i = \frac{|D_i|}{|D|}$ - ratio of instances classified as i

Impurity measure $I(D)$

- Measures the degree of mixing of the two classes in D
- The impurity measure should satisfy:
 - Largest when data are split evenly for attribute values

$$p_i = \frac{1}{\text{number of classes}}$$

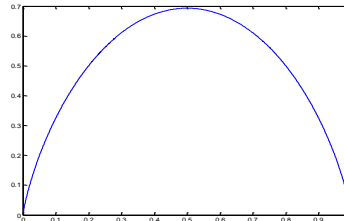
- Should be 0 when all data belong to the same class

Impurity measures

- There are various impurity measures used in the literature
 - **Entropy based measure (Quinlan, C4.5)**

$$I(D) = Entropy(D) = -\sum_{i=1}^k p_i \log p_i$$

Example for k=2



- **Gini measure (Breiman, CART)**

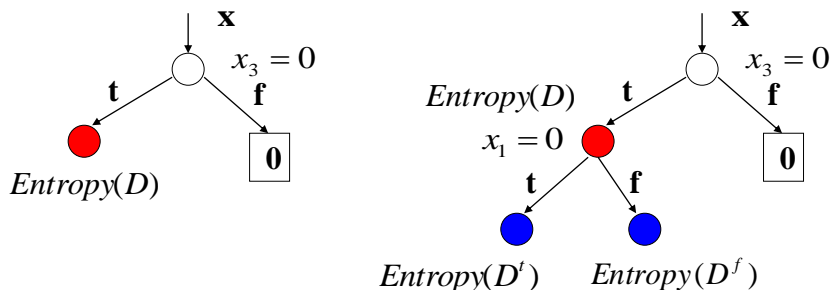
$$I(D) = Gini(D) = 1 - \sum_{i=1}^k p_i^2$$

Impurity measures

- **Gain due to split** – expected reduction in the impurity measure (entropy example)

$$\begin{array}{c} \text{Split condition} \\ \downarrow \\ \text{Gain}(D, A) = Entropy(D) - \sum_{v \in \text{Values}(A)} \frac{|D^v|}{|D|} Entropy(D^v) \end{array}$$

$|D^v|$ - a partition of D with the value of attribute $A = v$



Decision tree learning

- **Greedy learning algorithm:**

- Builds the tree in the top-down fashion
- Gradually expands the leaves of the partially built tree

Algorithm sketch:

- Repeat until no or small improvement in the impurity
- Find the attribute with the highest gain
 - Add the attribute to the tree and split the set accordingly

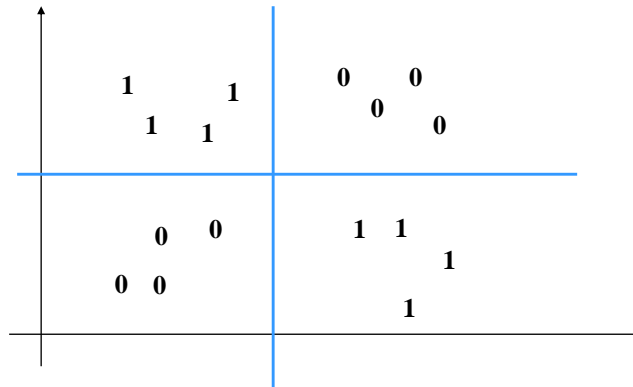
The method is greedy:

- It looks at a single attribute and gain in each step
- May fail when the combination of attributes is needed to improve the purity (parity functions)

Decision tree learning

- **Limitations of greedy methods**

Cases in which only a combination of two or more attributes improves the impurity



Decision tree learning

By reducing the impurity measure we can grow **very large trees**

Problem: Overfitting

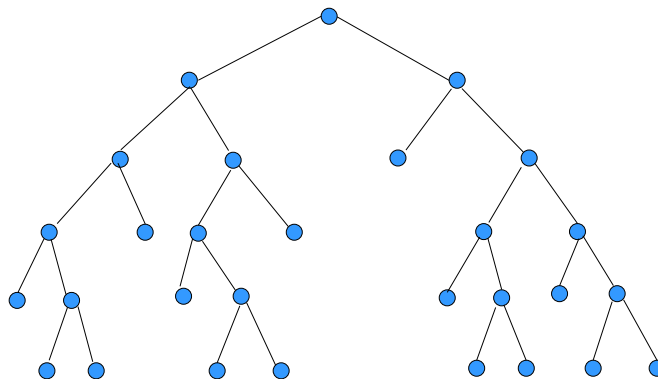
- We may split and classify very well the training set, but we may do worse in terms of the generalization error

Solutions to the overfitting problem:

- **Solution 1. Build the tree then prune the branches**
 - Build the tree, then eliminate leaves that overfit
 - Use **validation set** to test for the overfit
- **Solution 2. Prune while building the tree**
 - Test for the overfit in the tree building phase
 - Stop building the tree when performance on the **validation set** deteriorates

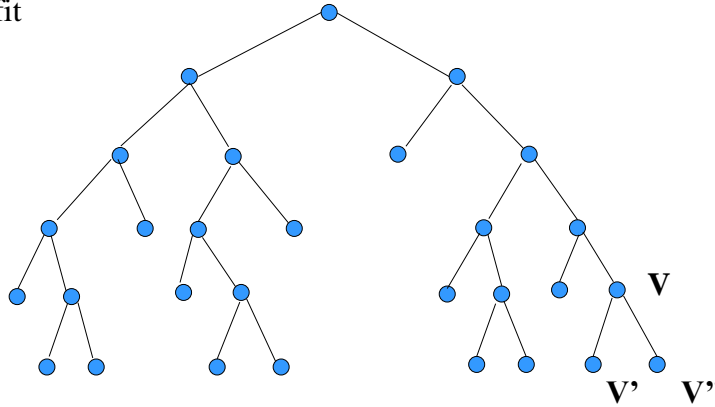
Decision tree learning

Backpruning: Prune branches of the tree built in the first phase in the bottom-up fashion by using the validation set to test for the overfit



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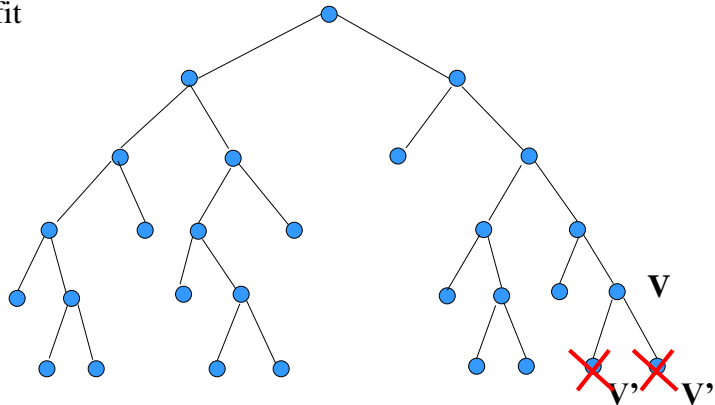
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Compare: $\# \text{Errors}(V)$ vs $\# \text{Error}(V') + \# \text{Errors}(V'')$

Decision tree learning

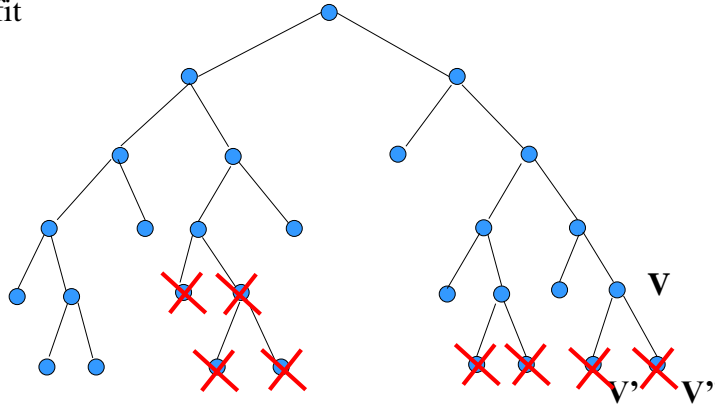
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