

CS 2750 Machine Learning

Lecture 2

Machine Learning

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Types of learning

- **Supervised learning**
 - Learning mapping between input x and desired output y
 - Teacher gives me y 's for the learning purposes
- **Unsupervised learning**
 - Learning relations between data components
 - No specific outputs given by a teacher
- **Reinforcement learning**
 - Learning mapping between input x and desired output y
 - Critic does not give me y 's but instead a signal (reinforcement) of how good my answer was
- **Other types of learning:**
 - **Concept learning, explanation-based learning, etc.**

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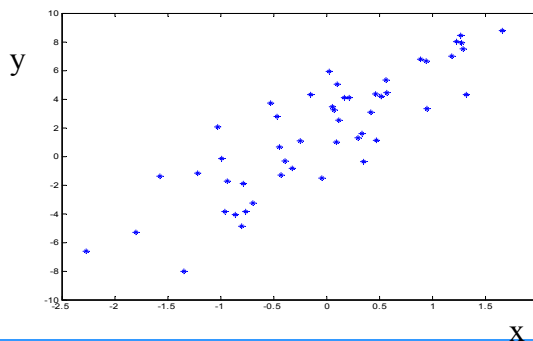
A learning system: basic cycle

1. **Data:** $D = \{d_1, d_2, \dots, d_n\}$
2. **Model selection:**
 - **Select a model** or a set of models (with parameters)
E.g. $y = ax + b$
3. **Choose the objective function**
 - **Squared error** $\frac{1}{n} \sum_{i=1}^n (y_i - f(x_i))^2$
4. **Learning:**
 - **Find the set of parameters optimizing the error function**
 - The model and parameters with the smallest error
5. **Testing:**
 - **Apply the learned model to new data**
 - E.g. predict y s for new inputs x using learned $f(x)$
 - Evaluate on the test data

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- **Squared error**

4. **Learning:**

- **Find the set**

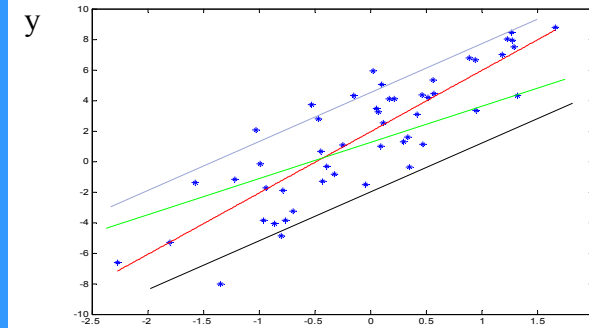
- The model

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- **Apply to**

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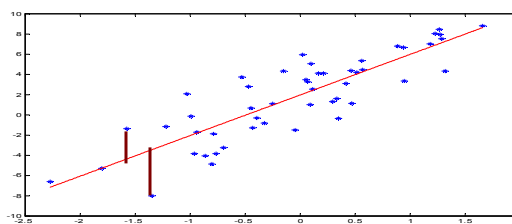
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5. **Testing:**

- **Apply to**

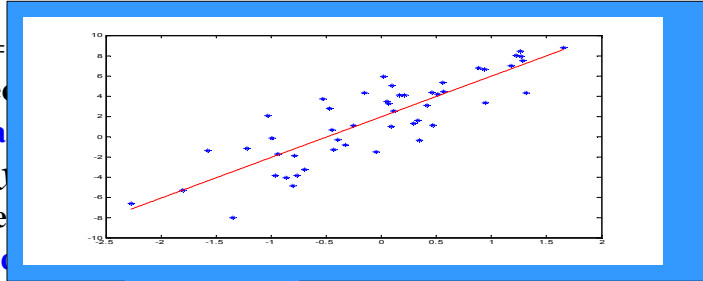
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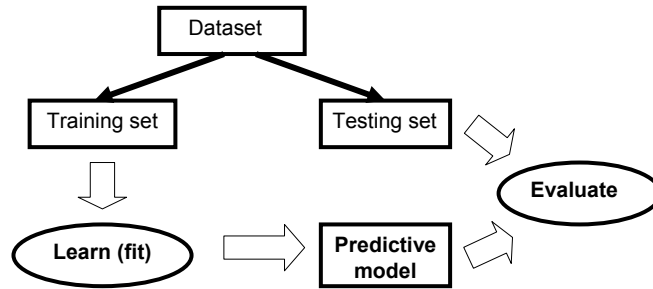
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Testing of learning models

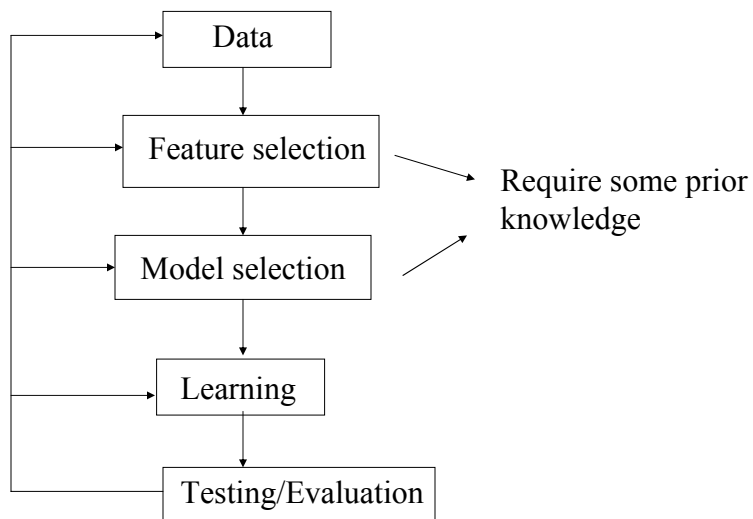
- **Simple holdout method**

- Divide the data to the training and test data

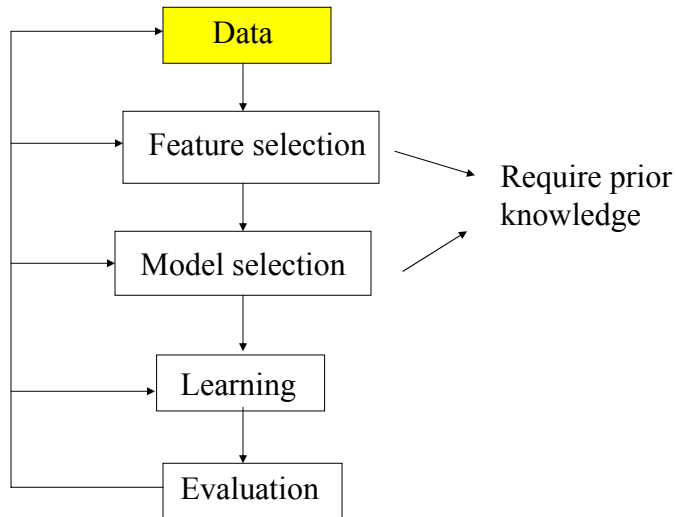


- Typically 2/3 training and 1/3 testing

Design cycle



Design cycle



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Data

Data may need a lot of:

- Cleaning
- Preprocessing (conversions)

Cleaning:

- Get rid of errors, noise,
- Removal of redundancies

Preprocessing:

- Renaming
- Rescaling (normalization)
- Discretization
- Abstraction
- Aggregation
- New attributes

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Data preprocessing

- **Renaming** (relabeling) categorical values to numbers
 - dangerous in conjunction with some learning methods
 - numbers will impose an order that is not warranted

High \rightarrow 2

Normal \rightarrow 1

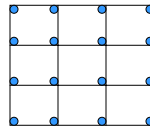
Low \rightarrow 0

True \rightarrow 2

False \rightarrow 1

Unknown \rightarrow 0

- **Rescaling (normalization)**: continuous values transformed to some range, typically $[-1, 1]$ or $[0, 1]$.
- **Discretizations (binning)**: continuous values to a finite set of discrete values



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Data preprocessing

- **Abstraction**: merge together categorical values
- **Aggregation**: summary or aggregation operations, such minimum value, maximum value, average etc.
- **New attributes**:
 - example: obesity-factor = weight/height

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Data biases

- **Watch out for data biases:**
 - Try to understand the data source
 - Make sure the data we make conclusions on are the same as data we used in the analysis
 - It is very easy to derive “unexpected” results when data used for analysis and learning are biased (pre-selected)
- **Results (conclusions) derived for biased data do not hold in general !!!**

Data biases

Example 1: Risks in pregnancy study

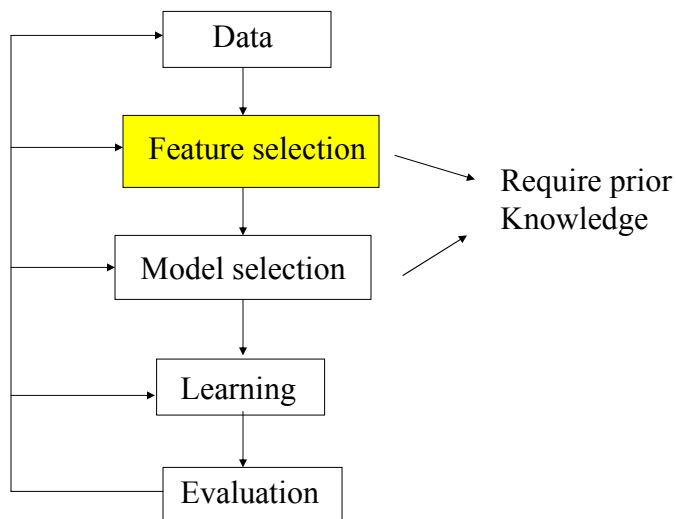
- Sponsored by DARPA at military hospitals
- Study of a large sample of pregnant woman who visited military hospitals
- **Conclusion:** the factor with the largest impact on reducing risks during pregnancy (statistically significant) is a pregnant woman being single
- a woman that is single → the smallest risk
- What is wrong?

Data

Example 2: Stock market trading (example by Andrew Lo)

- Data on stock performances of companies traded on stock market over past 25 year
- **Investment goal:** pick a stock to hold long term
- **Proposed strategy:** invest in a company stock with an IPO corresponding to a Carmichael number
- **Evaluation result:** excellent return over 25 years
- Where the magic comes from?

Design cycle

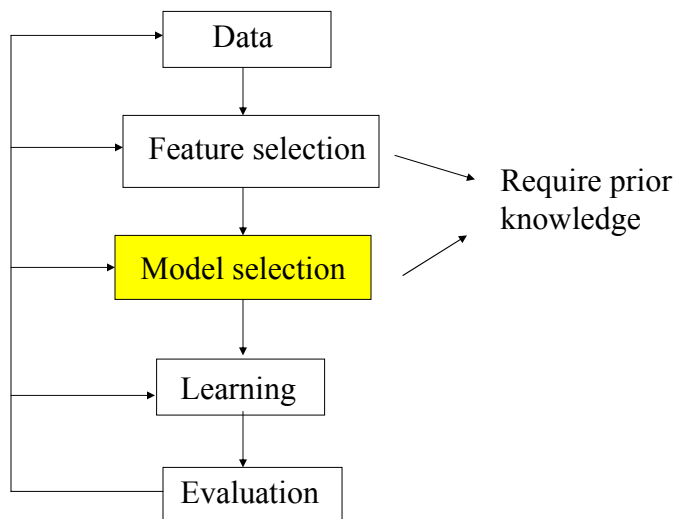


Feature selection

- **The size (dimensionality) of a sample** can be enormous
$$x_i = (x_i^1, x_i^2, \dots, x_i^d)$$
 d - very large
- **Example: document classification**
 - **thousands of documents**
 - 10,000 different words
 - **Features/Inputs:** counts of occurrences of different words
 - Overfit threat - too many parameters to learn, not enough samples to justify the estimates the parameters of the model
- **Feature selection: reduces the feature sets**
 - **Methods for removing input features**

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Design cycle



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Model selection

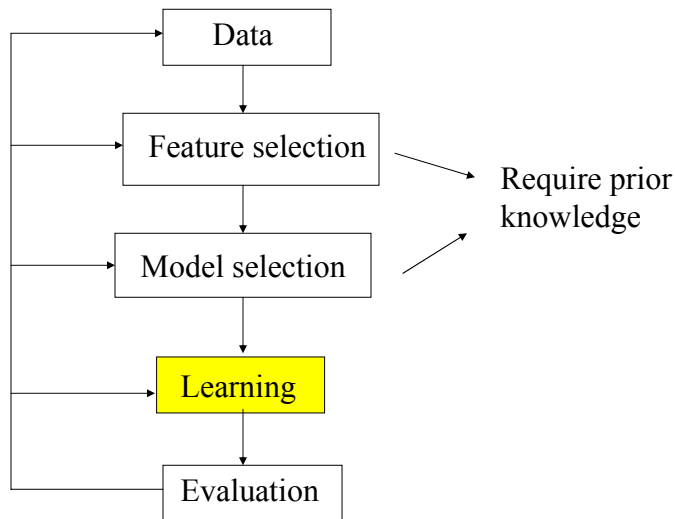
- **What is the right model to learn?**
 - A prior knowledge helps a lot, but still a lot of guessing
 - Initial data analysis and visualization
 - We can make a good guess about the form of the distribution, shape of the function
 - Independences and correlations
- **Overfitting problem**
 - Take into account the **bias and variance** of error estimates
 - Simpler (more biased) model – parameters can be estimated more reliably (smaller variance of estimates)
 - Complex model with many parameters – parameter estimates are less reliable (large variance of the estimate)

Solutions for overfitting

How to make the learner avoid the overfit?

- **Assure sufficient number of samples** in the training set
 - May not be possible (small number of examples)
- **Hold some data out of the training set = validation set**
 - Train (fit) on the training set (w/o data held out);
 - Check for the generalization error on the validation set, choose the model based on the validation set error (random re-sampling validation techniques)
- **Regularization (Occam's Razor)**
 - Explicit preference towards simple models
 - Penalize for the model complexity (number of parameters) in the objective function

Design cycle



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Learning

- **Learning = optimization problem.** Various criteria:

- **Mean square error**

$$\mathbf{w}^* = \arg \min_{\mathbf{w}} \text{Error}(\mathbf{w}) \quad \text{Error}(\mathbf{w}) = \frac{1}{N} \sum_{i=1, \dots, N} (y_i - f(x_i, \mathbf{w}))^2$$

- **Maximum likelihood (ML) criterion**

$$\Theta^* = \arg \max_{\Theta} P(D | \Theta) \quad \text{Error}(\Theta) = -\log P(D | \Theta)$$

- **Maximum posterior probability (MAP)**

$$\Theta^* = \arg \max_{\Theta} P(\Theta | D) \quad P(\Theta | D) = \frac{P(D | \Theta)P(\Theta)}{P(D)}$$

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Learning

Learning = optimization problem

- Optimization problems can be hard to solve. Right choice of a model and an error function makes a difference.
- **Parameter optimizations (continuous space)**
 - Linear programming, Convex programming
 - Gradient methods: grad. descent, Conjugate gradient
 - Newton-Raphson (2nd order method)
 - Levenberg-MarquardSome can be carried **on-line** on a sample by sample basis
- **Combinatorial optimizations (over discrete spaces):**
 - Hill-climbing
 - Simulated-annealing
 - Genetic algorithms

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Parametric optimizations

- Sometimes can be solved directly but this depends on the objective function and the model
 - **Example:** squared error criterion for linear regression
- Very often the error function to be optimized is not that nice.

$$\text{Error}(\mathbf{w}) = f(\mathbf{w}) \quad \mathbf{w} = (w_0, w_1, w_2 \dots w_k)$$

- a complex function of weights (parameters)

$$\text{Goal: } \mathbf{w}^* = \arg \min_{\mathbf{w}} f(\mathbf{w})$$

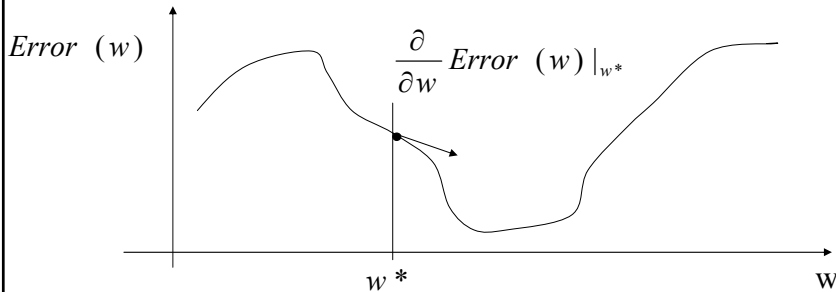
- **Example of a possible method: Gradient-descent method**

Idea: move the weights (free parameters) gradually in the error decreasing direction

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Gradient descent method

- Descend to the minimum of the function using the gradient information

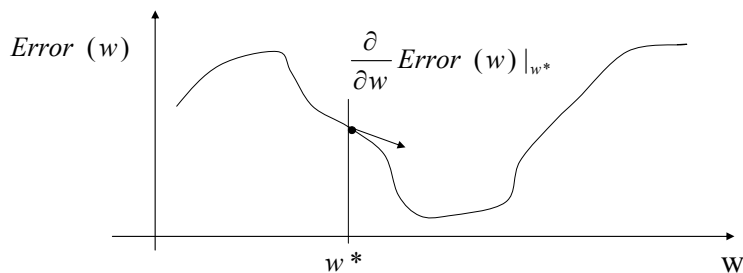


- Change the parameter value of w according to the gradient

$$w \leftarrow w^* - \alpha \frac{\partial}{\partial w} Error(w) |_{w^*}$$

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Gradient descent method



- New value of the parameter

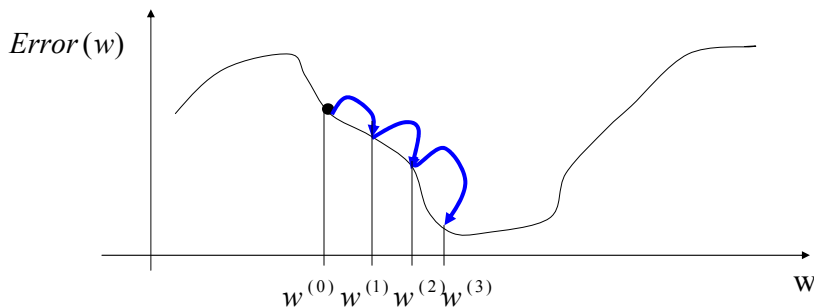
$$w \leftarrow w^* - \alpha \frac{\partial}{\partial w} Error(w) |_{w^*}$$

$\alpha > 0$ - a learning rate (scales the gradient changes)

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Gradient descent method

- To get to the function minimum repeat (iterate) the gradient based update few times



- **Problems:** local optima, saddle points, slow convergence
- More complex optimization techniques use additional information (e.g. second derivatives)

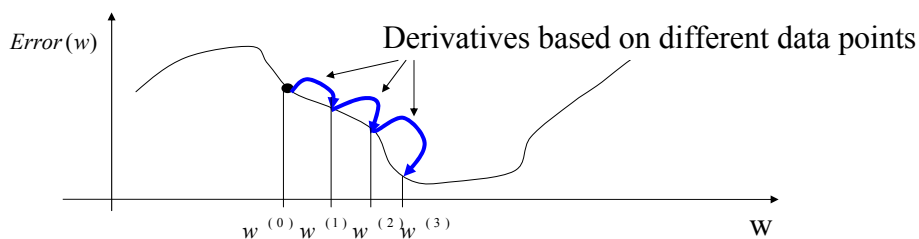
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On-line learning (optimization)

- Error function looks at all data points at the same time
E.g. $Error(\mathbf{w}) = \frac{1}{n} \sum_{i=1 \dots n} (y_i - f(x_i, \mathbf{w}))^2$
- **On-line error** - separates the contribution from a data point

$$Error_{\text{ON-LINE}}(\mathbf{w}) = (y_i - f(x_i, \mathbf{w}))^2$$

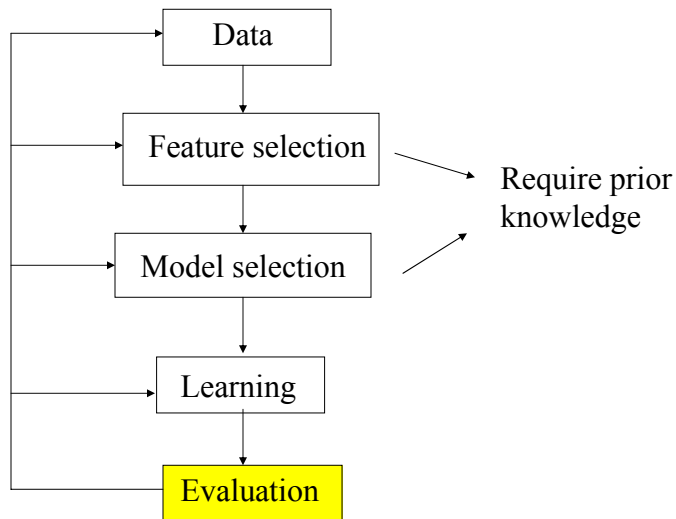
- **Example: On-line gradient descent**



- **Advantages:** 1. simple learning algorithm
2. no need to store data (on-line data streams)

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Design cycle

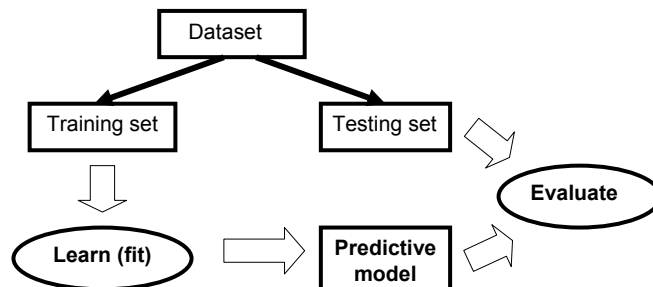


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Evaluation of learning models

- **Simple holdout method**

- Divide the data to the training and test data



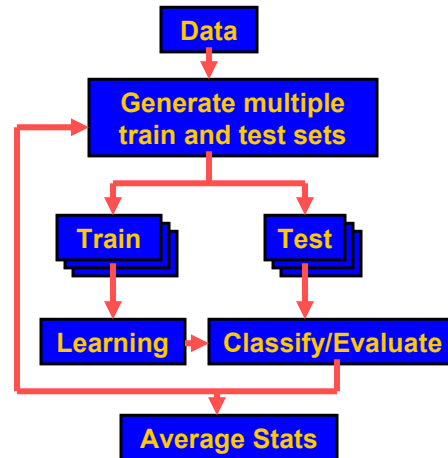
- Typically 2/3 training and 1/3 testing

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Evaluation

Other more complex methods

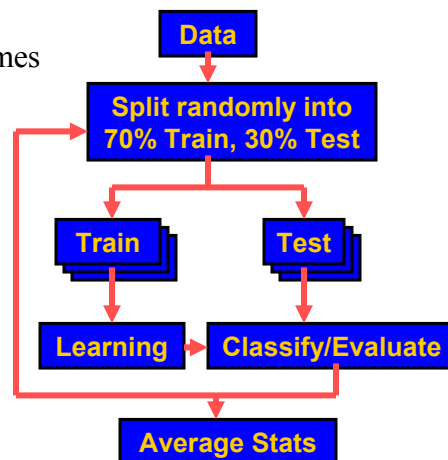
- Use multiple train/test sets
- Based on various random re-sampling schemes:
 - Random sub-sampling
 - Cross-validation
 - Bootstrap



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Evaluation

- **Random sub-sampling**
 - Repeat a simple holdout method k times

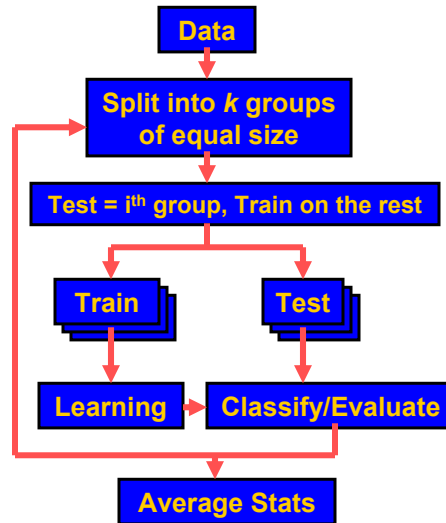


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Evaluation

Cross-validation (k-fold)

- Divide data into k disjoint groups, test on k -th group/train on the rest
- Typically 10-fold cross-validation
- Leave one out cross-validation ($k = \text{size of the data } D$)

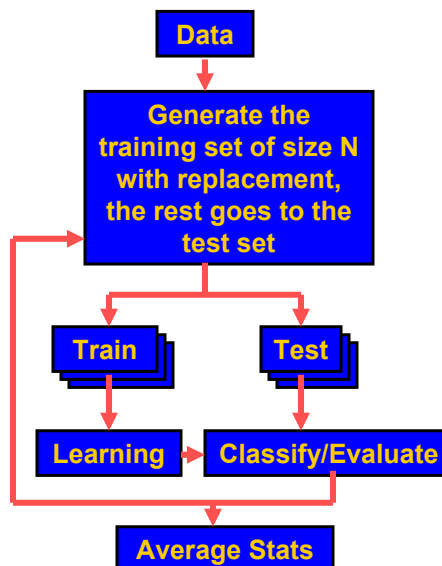


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Evaluation

Bootstrap

- The training set of size $N = \text{size of the data } D$
- Sampling with the replacement



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Evaluation

- What if we want to compare the predictive performance on a classification or a regression problem for two different learning methods?
- **Solution:** compare the error results on the test data set or the average statistics on the same training/testing data splits
- **Answer:** the method with better (smaller) testing error gives a better generalization error.
- But we need to use statistics to validate the choice

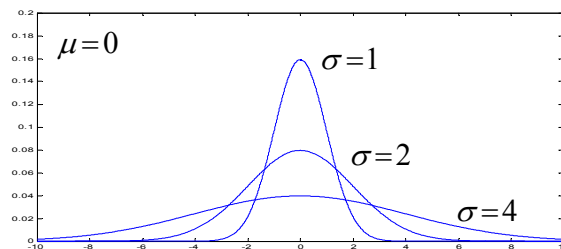
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Evaluation

- **Problem:** we cannot be 100 % sure about generalization errors
- **Solution:** test the statistical significance of the result
- **Central limit theorem:**

Let random variables X_1, X_2, \dots, X_n form a random sample from a distribution with mean μ and variance σ^2 , then if the sample n is large, the distribution

$$\sum_{i=1}^n X_i \approx N(n\mu, n\sigma^2) \quad \text{or} \quad \frac{1}{n} \sum_{i=1}^n X_i \approx N(\mu, \sigma^2 / n)$$



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Statistical significance test

- **Sample mean:** $\frac{1}{n} \sum_{i=1}^n X_i$

$$\frac{1}{n} \sum_{i=1}^n X_i \approx N(\mu, \sigma^2 / n) \quad X_i \text{ - Is a random variable}$$

- **Assume:**

Regression learner 1 uses function $f_1(\mathbf{x})$ to predict y s

Regression learner 2 uses function $f_2(\mathbf{x})$ to predict y s

$$Error_1 = \frac{1}{n} \sum_{i=1}^n (y_i - f_1(\mathbf{x}_i))^2 \quad Error_2 = \frac{1}{n} \sum_{i=1}^n (y_i - f_2(\mathbf{x}_i))^2$$

$$\Delta Error = \frac{1}{n} \sum_{i=1}^n [(y_i - f_1(\mathbf{x}_i))^2 - (y_i - f_2(\mathbf{x}_i))^2]$$

$$X_i \rightarrow (y_i - f_1(\mathbf{x}_i))^2 - (y_i - f_2(\mathbf{x}_i))^2$$

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Statistical significance test

- **Two learners are the same in terms of the generalization error when**

$$E_{(x,y)}(y - f_1(\mathbf{x}))^2 = E_{(x,y)}(y - f_2(\mathbf{x}))^2$$

$$E_{(x,y)}[(y - f_1(\mathbf{x}))^2 - (y - f_2(\mathbf{x}))^2] = \mu_{diff} = 0$$

- **Sample mean** (estimate of the last quantity)

$$\Delta Error = \frac{1}{n} \sum_{i=1}^n [(y_i - f_1(\mathbf{x}_i))^2 - (y_i - f_2(\mathbf{x}_i))^2]$$

$$\Delta Error \approx N(\mu_{diff}, \sigma_{diff}^2 / n)$$

- **Statistical tests for the mean**

- **H0 (null hypothesis)** $\mu_{diff}^0 = 0$
- **H1 (alternative hypothesis)** $\mu_{diff}^0 \neq 0$

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Statistical significance test

- **Statistical tests for the mean**

- **H0 (null hypothesis)**

$$\mu_{diff}^0 = 0$$

- **H1 (alternative hypothesis)**

$$\mu_{diff}^0 \neq 0$$

- **Basic idea:**

we use the sample mean and check how probable it is to occur given that the true mean is 0

$$E_{(x,y)}[(y - f_1(x))^2 - (y - f_2(x))^2] = \mu_{diff} = 0$$

$$\Delta Error = \bar{X} = \frac{1}{n} \sum_{i=1}^n [(y_i - f_1(x_i))^2 - (y_i - f_2(x_i))^2]$$

If the probability that $\Delta Error$ comes from the normal distribution with mean 0 is small – we reject the null hypothesis on that probability level

Statistical significance test

- **Statistical tests for the mean**

- **H0 (null hypothesis)**

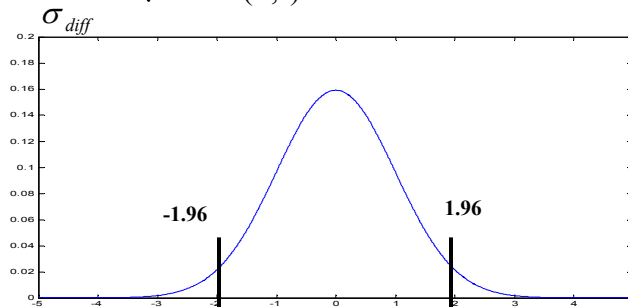
$$\mu_{diff}^0 = 0$$

- **H1 (alternative hypothesis)**

$$\mu_{diff}^0 \neq 0$$

- **Assume we know standard deviation** σ_{diff}

$$z = \frac{\bar{X} - \mu_{diff}^0}{\sigma_{diff}} \sqrt{n} \approx N(0,1) \quad \text{with} \quad P=0.95 \quad z \in [-1.96, 1.96]$$

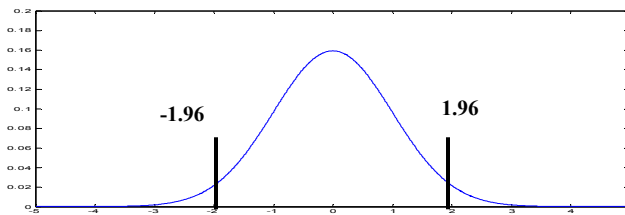


Statistical significance test

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- **Z-test: If z is outside of the interval – reject the null hypothesis at significance level 5 %**



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Statistical significance test

- **Statistical tests for the mean**
 - **H0 (null hypothesis)** $\mu_{diff}^0 = 0$
- **Problem: we do not know the standard deviation** σ_{diff}

- **Solution:** $t = \frac{\bar{X} - \mu_{diff}^0}{S_{diff}} \sqrt{n} \approx t\text{-distribution (Student distribution)}$

$$S_{diff} = \sqrt{\frac{\sum_{i=1}^n (X_i - \bar{X})^2}{n-1}} \quad \text{- Estimate of the standard deviation}$$

- **T-test: If t is outside of the tabulated interval reject the null hypothesis at the corresponding significance level**

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