

CS 2750 Machine Learning

Lecture 13

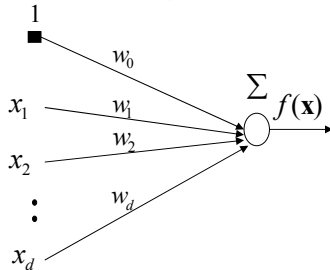
Multi-layer Neural Networks

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Limitations of basic linear units

Linear regression

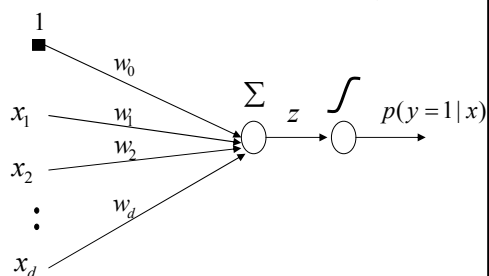
$$f(\mathbf{x}) = w_0 + \sum_{j=1}^d w_j x_j$$



Function linear in inputs !!

Logistic regression

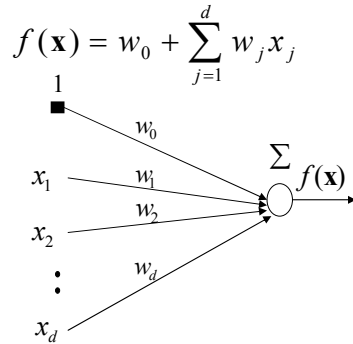
$$f(\mathbf{x}) = p(y=1 | \mathbf{x}, \mathbf{w}) = g(w_0 + \sum_{j=1}^d w_j x_j)$$



Linear decision boundary !!

Linear units

Linear regression

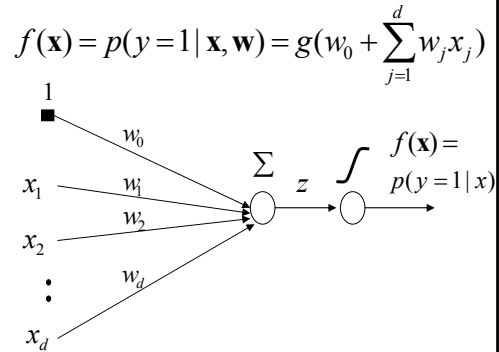


On-line gradient update:

$$w_0 \leftarrow w_0 + \alpha(y - f(\mathbf{x}))$$

$$w_j \leftarrow w_j + \alpha(y - f(\mathbf{x}))x_j$$

Logistic regression



On-line gradient update:

$$w_0 \leftarrow w_0 + \alpha(y - f(\mathbf{x}))$$

$$w_j \leftarrow w_j + \alpha(y - f(\mathbf{x}))x_j$$

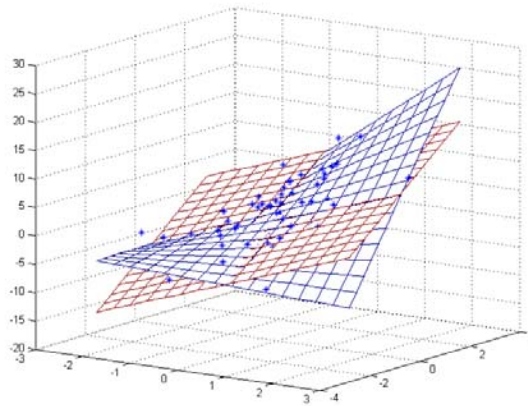
The same

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Regression with the quadratic model.

Limitation: linear hyper-plane only

- a non-linear surface can be better

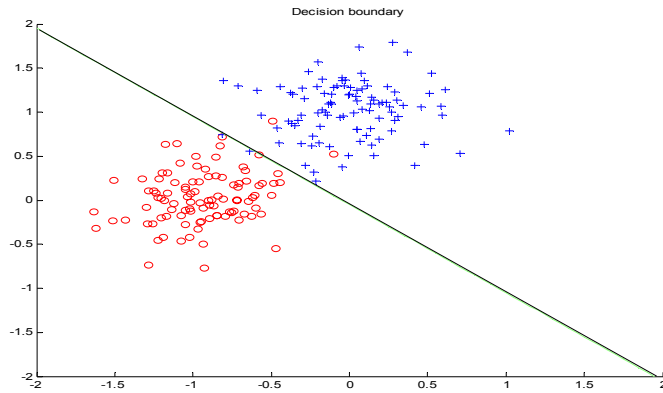


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Classification with the linear model.

Logistic regression model defines a linear decision boundary

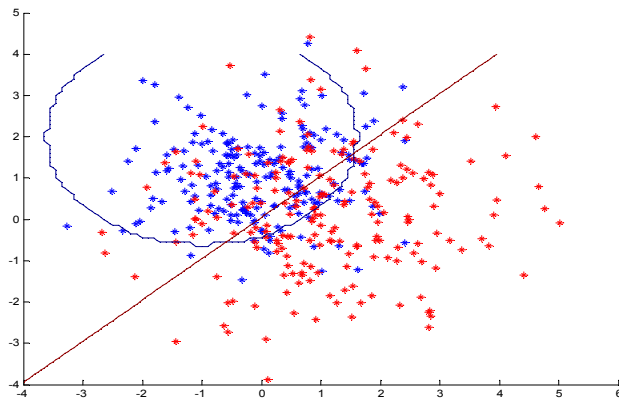
- Example: 2 classes (blue and red points)



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Linear decision boundary

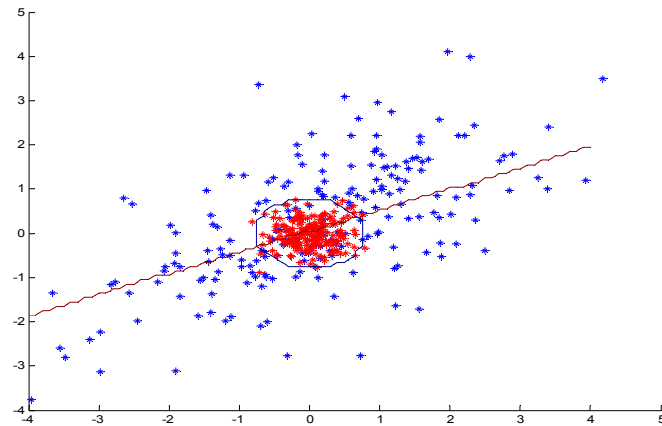
- logistic regression model is not optimal, but not that bad



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When logistic regression fails?

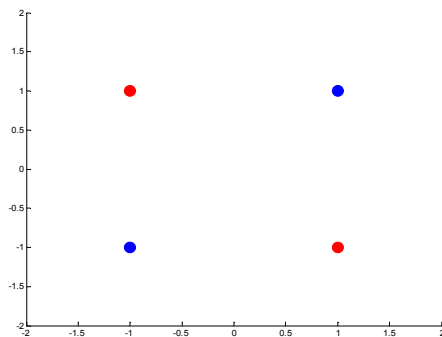
- Example in which the logistic regression model fails



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Limitations of linear units.

- Logistic regression does not work for **parity functions**
- no linear decision boundary exists



Solution: a model of a non-linear decision boundary

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Extensions of simple linear units

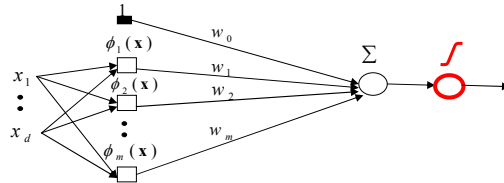
Feature (basis) functions model **nonlinearities**

Linear regression

$$f(\mathbf{x}) = w_0 + \sum_{j=1}^m w_j \phi_j(\mathbf{x})$$

Logistic regression

$$f(\mathbf{x}) = g\left(w_0 + \sum_{j=1}^m w_j \phi_j(\mathbf{x})\right)$$



Important property:

- The same problem as learning of the weights for linear units, the input has changed– but the weights are linear in the new input

Problem: too many weights to learn

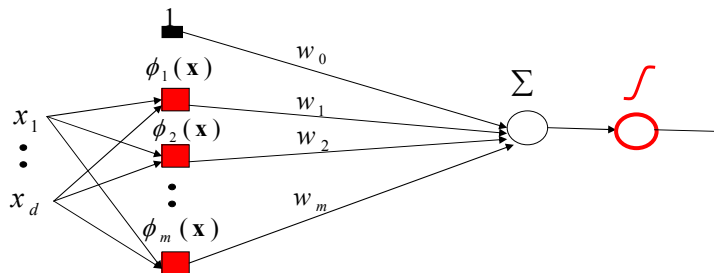
Multi-layer neural networks

• **Problems of extended linear units:**

- fixed basis functions,
- too many weights

• **One possible solution:**

- Assume parametric feature (basis) functions
- Learn the parameters together with the remaining weights

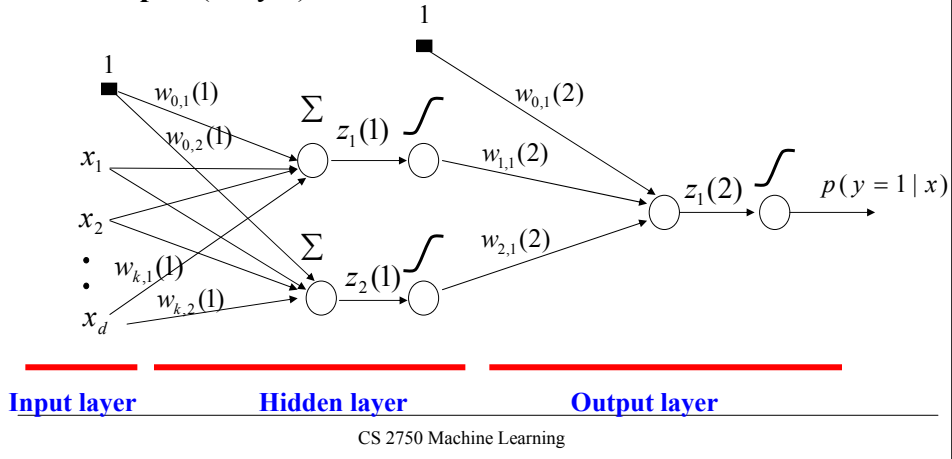


Multilayer neural network

Also called a **multilayer perceptron (MLP)**

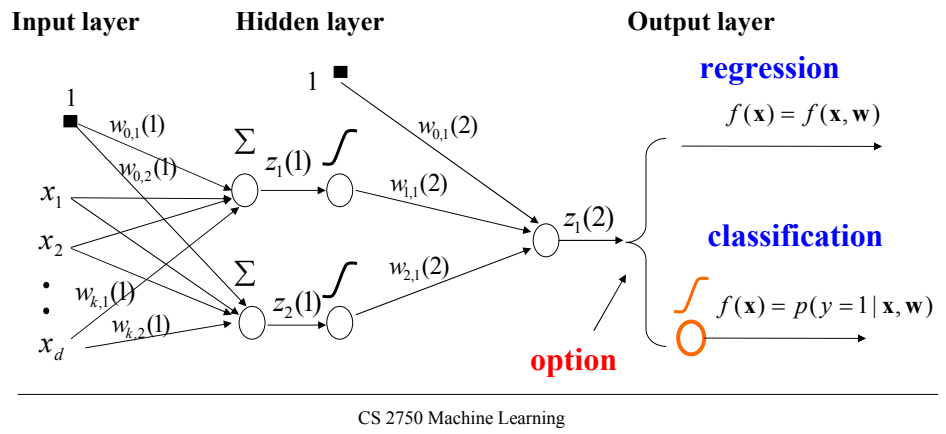
Cascades multiple logistic regression units

Example: (2 layer) classifier with non-linear decision boundaries



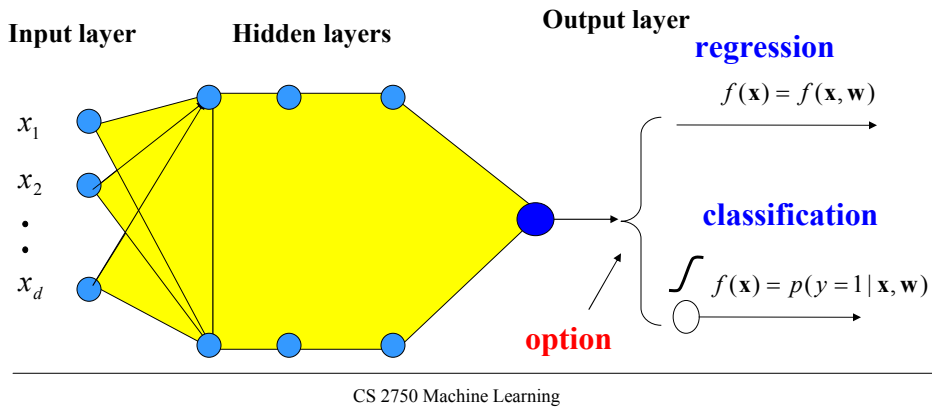
Multilayer neural network

- Models **non-linearities through logistic regression units**
- Can be applied to both **regression and binary classification problems**



Multilayer neural network

- **Non-linearities are modeled using multiple hidden logistic regression units (organized in layers)**
- The output layer determines whether it is a **regression or a binary classification problem**

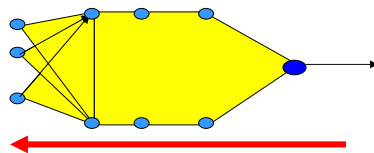


Learning with MLP

- How to learn the parameters of the neural network?
- **On-line gradient descent algorithm**
 - Weight updates based on the error: $J_{\text{online}}(D_i, \mathbf{w})$

$$w_j \leftarrow w_j - \alpha \frac{\partial}{\partial w_j} J_{\text{online}}(D_i, \mathbf{w})$$

- We need to **compute gradients for weights in all units**
- **Can be computed in one backward sweep through the net !!!**



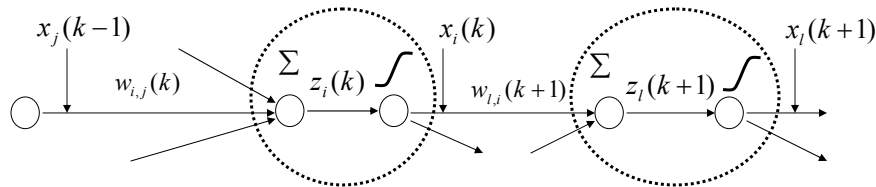
- The process is called **back-propagation**

Backpropagation

(k-1)-th level

k-th level

(k+1)-th level



$x_i(k)$ - output of the unit i on level k

$z_i(k)$ - input to the sigmoid function on level k

$w_{i,j}(k)$ - weight between units j and i on levels $(k-1)$ and k

$$z_i(k) = w_{i,0}(k) + \sum_j w_{i,j}(k)x_j(k-1)$$

$$x_i(k) = g(z_i(k))$$

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Backpropagation

Update weight $w_{i,j}(k)$ using a data point $D_u = \langle \mathbf{x}, y \rangle$

$$w_{i,j}(k) \leftarrow w_{i,j}(k) - \alpha \frac{\partial}{\partial w_{i,j}(k)} J_{online}(D_u, \mathbf{w})$$

$$\text{Let } \delta_i(k) = \frac{\partial}{\partial z_i(k)} J_{online}(D_u, \mathbf{w})$$

$$\text{Then: } \frac{\partial}{\partial w_{i,j}(k)} J_{online}(D_u, \mathbf{w}) = \frac{\partial J_{online}(D_u, \mathbf{w})}{\partial z_i(k)} \frac{\partial z_i(k)}{\partial w_{i,j}(k)} = \delta_i(k)x_j(k-1)$$

S.t. $\delta_i(k)$ is computed from $x_i(k)$ and the next layer $\delta_l(k+1)$

$$\delta_i(k) = \left[\sum_l \delta_l(k+1)w_{l,i}(k+1) \right] x_i(k)(1-x_i(k))$$

Last unit (is the same as for the regular linear units):

$$\delta_i(K) = -(y - f(\mathbf{x}, \mathbf{w}))$$

It is the same for the classification with the log-likelihood measure of fit and linear regression with least-squares error!!!

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Learning with MLP

- **Online gradient descent algorithm**

- Weight update for example D_u :

$$w_{i,j}(k) \leftarrow w_{i,j}(k) - \alpha \frac{\partial}{\partial w_{i,j}(k)} J_{\text{online}}(D_u, \mathbf{w})$$

$$\frac{\partial}{\partial w_{i,j}(k)} J_{\text{online}}(D_u, \mathbf{w}) = \frac{\partial J_{\text{online}}(D_u, \mathbf{w})}{\partial z_i(k)} \frac{\partial z_i(k)}{\partial w_{i,j}(k)} = \delta_i(k) x_j(k-1)$$

$$w_{i,j}(k) \leftarrow w_{i,j}(k) - \alpha \delta_i(k) x_j(k-1)$$

$x_j(k-1)$ - j-th output of the (k-1) layer

$\delta_i(k)$ - derivative computed via backpropagation

α - a learning rate

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Online gradient descent algorithm for MLP

Online-gradient-descent (D , number of iterations)

Initialize all weights $w_{i,j}(k)$

for $i=1:1$: number of iterations

do **select** a data point $D_u = \langle \mathbf{x}, y \rangle$ from D

set learning rate α

compute outputs $x_j(k)$ for each unit

compute derivatives $\delta_i(k)$ via **backpropagation**

update all weights (in parallel)

$$w_{i,j}(k) \leftarrow w_{i,j}(k) - \alpha \delta_i(k) x_j(k-1)$$

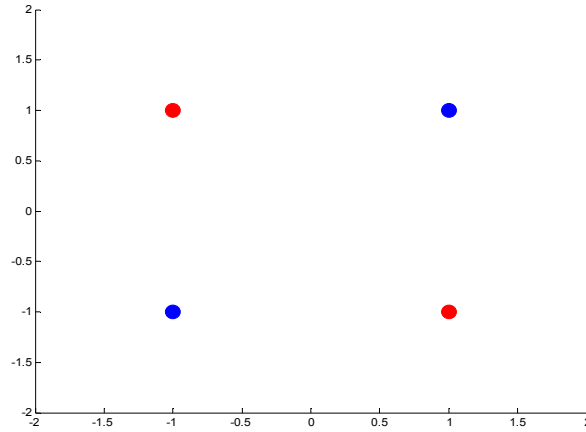
end for

return weights \mathbf{w}

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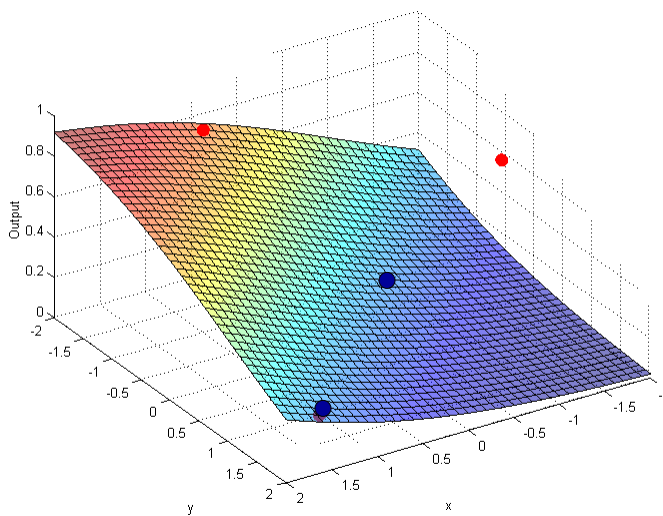
Xor Example.

- linear decision boundary does not exist



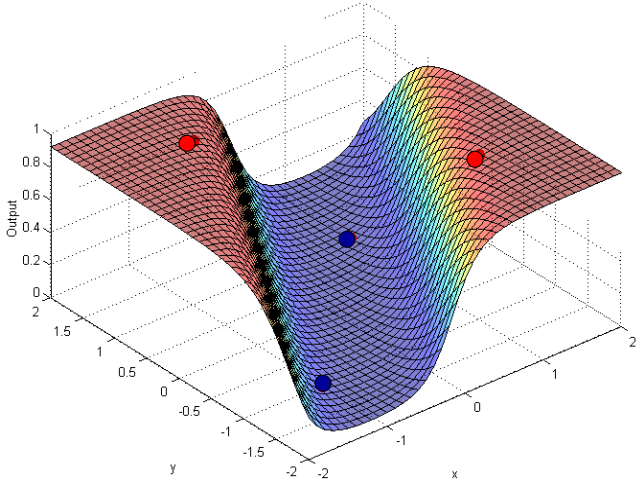
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Xor example. Linear unit



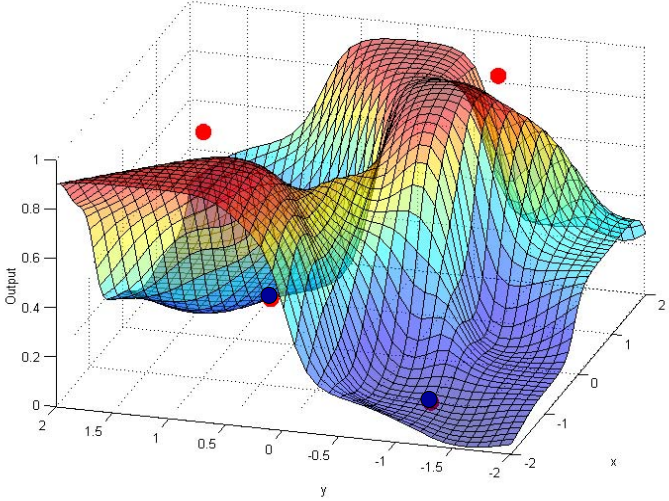
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Xor example.
Neural network with 2 hidden units



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Xor example.
Neural network with 10 hidden units



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MLP in practice

- **Optical character recognition** – digits 20x20
 - Automatic sorting of mails
 - 5 layer network with multiple output functions

