

## CS 2750 Machine Learning Lecture 15

### Density estimation with hidden variables and missing values

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## Project proposals

**Due: Monday, March 24, 2003**

- **1-2 pages long**

### Proposal

- **Written proposal:**
  1. Outline of a learning problem, type of data you have available. Why is the problem important?
  2. Learning methods you plan to try and implement for the problem. References to previous work.
  3. How do you plan to test, compare learning approaches
  4. Schedule of work (approximate timeline of work)
- **Short 5 minute PPT presentation summarizing points 1-4**
  - **Make it ready through internet**

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## Learning probability distribution

### Basic learning settings:

- A set of random variables  $\mathbf{X} = \{X_1, X_2, \dots, X_n\}$
- **A model of the distribution** over variables in  $\mathbf{X}$  with parameters  $\Theta$
- **Data**  $D = \{D_1, D_2, \dots, D_N\}$   
s.t.  $D_i = (x_1^i, x_2^i, \dots, x_n^i)$

**Objective:** find parameters  $\hat{\Theta}$  that describe the data

### Assumptions considered so far:

- Known parameterizations
- No hidden variables
- No-missing values

## Hidden variables

### Modeling assumption:

Variables  $\mathbf{X} = \{X_1, X_2, \dots, X_n\}$  are related through hidden variables

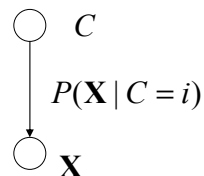
### Why to add hidden variables?

- **More flexibility in describing the distribution**  $P(\mathbf{X})$
- **Smaller parameterization of**  $P(\mathbf{X})$ 
  - **New independences can be introduced via hidden variables**

### Example:

- Latent variable models
  - hidden classes (categories)

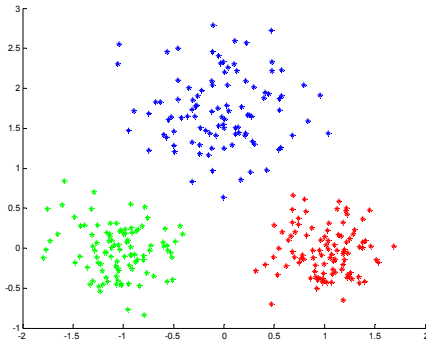
Hidden class variable



## Hidden variable model. Example.

- We want to represent the probability model of a population in a two dimensional space  $\mathbf{X} = \{X_1, X_2\}$

### Observed data

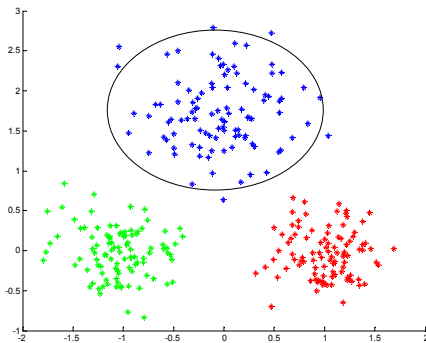


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## Hidden variable model

- We want to represent the probability model of a population in a two dimensional space  $\mathbf{X} = \{X_1, X_2\}$

### Observed data

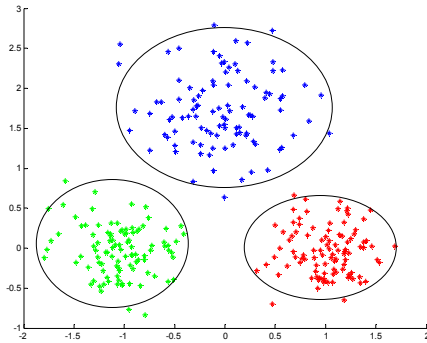


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## Hidden variable model

- We want to represent the probability model of a population in a two dimensional space  $\mathbf{X} = \{X_1, X_2\}$

### Observed data

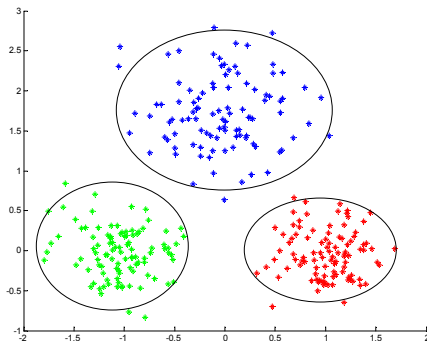


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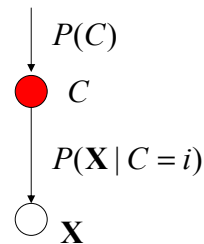
## Hidden variable model

- We want to represent the probability model of a population in a two dimensional space  $\mathbf{X} = \{X_1, X_2\}$

### Observed data



Model : 3 Gaussians with a hidden class variable



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## Mixture of Gaussians

Probability of the occurrence of a data point  $\mathbf{x}$  is modeled as

$$p(\mathbf{x}) = \sum_{i=1}^k p(C = i) p(\mathbf{x} | C = i)$$

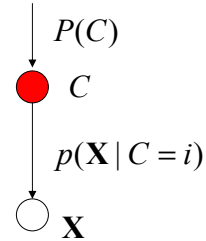
where

$$p(C = i)$$

= probability of a data point coming from class  $C=i$

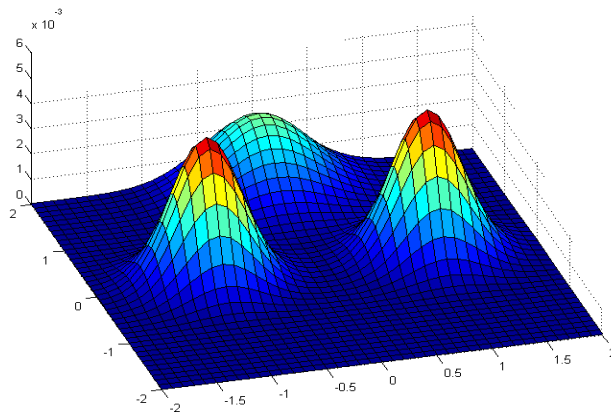
$$p(\mathbf{x} | C = i) \approx N(\boldsymbol{\mu}_i, \boldsymbol{\Sigma}_i)$$

= class-conditional density (modeled as Gaussian) for class  $i$



## Mixture of Gaussians

- Density function for the Mixture of Gaussians model

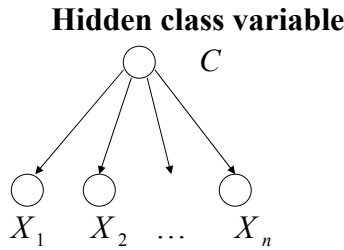


## Naïve Bayes with a hidden class variable

Introduction of a hidden variable can reduce the number of parameters defining  $P(\mathbf{X})$

**Example:**

- Naïve Bayes model with a hidden class variable



Attributes are independent given the class

- **Useful in customer profiles**
  - Class value = type of customers

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## Missing values

A set of random variables  $\mathbf{X} = \{X_1, X_2, \dots, X_n\}$

- **Data**  $D = \{D_1, D_2, \dots, D_N\}$

- **But some values are missing**

$$D_i = (x_1^i, x_3^i, \dots, x_n^i)$$

Missing value of  $x_2^i$

$$D_{i+1} = (x_3^i, \dots, x_n^i)$$

Missing values of  $x_1^i, x_2^i$

Etc.

- **Example: medical records**
- **We still want to estimate parameters of**  $P(\mathbf{X})$

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## Density estimation

**Goal:** Find the set of parameters  $\hat{\Theta}$

**Estimation criteria:**

- **ML**  $\max_{\Theta} p(D | \Theta, \xi)$
- **Bayesian**  $p(\Theta | D, \xi)$

**Optimization methods for ML:** gradient-ascent, conjugate gradient, Newton-Rhapson, etc.

- **Problem:** No or very small advantage from the structure of the corresponding belief network

**Expectation-maximization (EM) method**

- An alternative optimization method
- Suitable when there are missing or hidden values
- **Takes advantage of the structure of the belief network**

## General EM

**The key idea of a method:**

**Compute the parameter estimates** iteratively by performing the following two steps:

**Two steps of the EM:**

- 1. Expectation step.** Complete all hidden and missing variables with expectations for the current set of parameters  $\Theta'$
- 2. Maximization step.** Compute the new estimates of  $\Theta$  for the completed data

**Stop when no improvement possible**

## EM

Let  $H$  be a set of all variables with hidden or missing values

### Derivation

$$P(H, D | \Theta, \xi) = P(H | D, \Theta, \xi)P(D | \Theta, \xi)$$

$$\log P(H, D | \Theta, \xi) = \log P(H | D, \Theta, \xi) + \log P(D | \Theta, \xi)$$

$$\log P(D | \Theta, \xi) = \log P(H, D | \Theta, \xi) - \log P(H | D, \Theta, \xi)$$

 **Log-likelihood of data**

**Average both sides** with  $P(H | D, \Theta', \xi)$  for  $\Theta'$

$$E_{H|D, \Theta'} \log P(D | \Theta, \xi) = E_{H|D, \Theta'} \log P(H, D | \Theta, \xi) - E_{H|D, \Theta'} \log P(H | \Theta, \xi)$$

$$\log P(D | \Theta, \xi) = Q(\Theta | \Theta') + H(\Theta | \Theta')$$

**Log-likelihood of data**

## EM algorithm

**Algorithm** (general formulation)

Initialize parameters  $\Theta$

Repeat

Set  $\Theta' = \Theta$

**1. Expectation step**

$$Q(\Theta | \Theta') = E_{H|D, \Theta'} \log P(H, D | \Theta, \xi)$$

**2. Maximization step**

$$\Theta = \arg \max_{\Theta} Q(\Theta | \Theta')$$

until no or small improvement in  $\Theta$  ( $\Theta = \Theta'$ )

**Questions:** Why this leads to the ML estimate ?

What is the advantage of the algorithm?



## EM algorithm

- Why is the EM algorithm correct?
- **Claim: maximizing Q improves the log-likelihood**

$$l(\Theta) = Q(\Theta | \Theta') + H(\Theta | \Theta')$$

### Difference in log-likelihoods (current and next step)

$$l(\Theta) - l(\Theta') = Q(\Theta | \Theta') - Q(\Theta' | \Theta') + H(\Theta | \Theta') - H(\Theta' | \Theta')$$

**Subexpression**  $H(\Theta | \Theta') - H(\Theta' | \Theta') \geq 0$

**Kullback-Leibler (KL) divergence** (distance between 2 distributions)

$$KL(P | R) = \sum_i P_i \log \frac{P_i}{R_i} \geq 0 \quad \text{Is always positive !!!}$$

$$H(\Theta | \Theta') = -E_{H|D, \Theta'} \log P(H | \Theta, \xi) = -\sum_i p(H | D, \Theta') \log P(H | \Theta, \xi)$$

$$H(\Theta | \Theta') - H(\Theta' | \Theta') = \sum_i P(H | D, \Theta') \log \frac{P(H | \Theta', \xi)}{P(H | \Theta, \xi)} \geq 0$$

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## EM algorithm

### Difference in log-likelihoods

$$l(\Theta) - l(\Theta') = Q(\Theta | \Theta') - Q(\Theta' | \Theta') + H(\Theta | \Theta') - H(\Theta' | \Theta')$$

$$l(\Theta) - l(\Theta') \geq Q(\Theta | \Theta') - Q(\Theta' | \Theta')$$

**Thus**

by **maximizing Q we maximize the log-likelihood**

$$l(\Theta) = Q(\Theta | \Theta') + H(\Theta | \Theta')$$

EM is a first-order optimization procedure

- **Climbs the gradient**
- **Automatic learning rate**

**No need to adjust the learning rate !!!!**

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## EM advantages

### Key advantages:

- In many problems (e.g. Bayesian belief networks)

$$Q(\Theta | \Theta') = E_{H|D, \Theta'} \log P(H, D | \Theta, \xi)$$

- has a nice form and the maximization of Q can be carried in the closed form
- No need to compute Q before maximizing
- We directly optimize
  - use quantities corresponding to expected counts