

## CS 1571 Introduction to AI

### Lecture 25

- **Linear regression**
- **Logistic regression**

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## Supervised learning

**Data:**  $D = \{D_1, D_2, \dots, D_n\}$  a set of  $n$  examples

$D_i = \langle \mathbf{x}_i, y_i \rangle$

$\mathbf{x}_i = (x_{i,1}, x_{i,2}, \dots, x_{i,d})$  is an input vector of size  $d$

$y_i$  is the desired output (given by a teacher)

**Objective:** learn the mapping  $f : X \rightarrow Y$

s.t.  $y_i \approx f(\mathbf{x}_i)$  for all  $i = 1, \dots, n$

- **Regression:** Y is **continuous**

Example: earnings, product orders  $\rightarrow$  company stock price

- **Classification:** Y is **discrete**

Example: handwritten digit in binary form  $\rightarrow$  digit label

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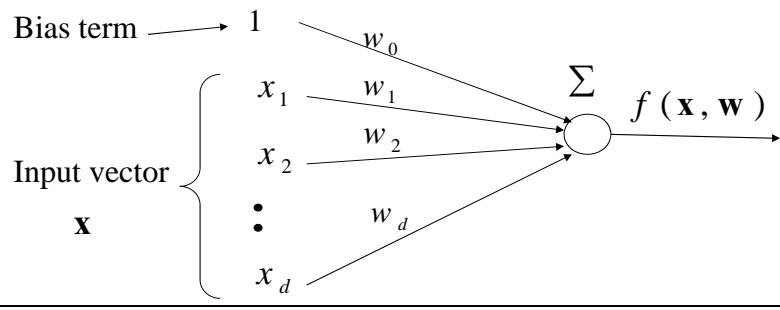
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## Linear regression

- **Function**  $f : X \rightarrow Y$  is a linear combination of input components

$$f(\mathbf{x}) = w_0 + w_1 x_1 + w_2 x_2 + \dots w_d x_d = w_0 + \sum_{j=1}^d w_j x_j$$

$w_0, w_1, \dots, w_d$  - parameters (weights)



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## Linear regression. Error.

- **Data:**  $D_i = \langle \mathbf{x}_i, y_i \rangle$
- **Function:**  $\mathbf{x}_i \rightarrow f(\mathbf{x}_i)$
- We would like to have  $y_i \approx f(\mathbf{x}_i)$  for all  $i = 1, \dots, n$
- **Error function** measures how much our predictions deviate from the desired answers

$$\text{Mean-squared error } J_n = \frac{1}{n} \sum_{i=1, \dots, n} (y_i - f(\mathbf{x}_i))^2$$

- **Learning:**

We want to find the weights minimizing the error !

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## Linear regression. Optimization.

- We want the **weights minimizing the error**

$$J_n = \frac{1}{n} \sum_{i=1..n} (y_i - f(\mathbf{x}_i))^2 = \frac{1}{n} \sum_{i=1..n} (y_i - \mathbf{w}^T \mathbf{x}_i)^2$$

- For the optimal set of parameters, derivatives of the error with respect to each parameter must be 0

$$\frac{\partial}{\partial w_j} J_n(\mathbf{w}) = -\frac{2}{n} \sum_{i=1}^n (y_i - w_0 x_{i,0} - w_1 x_{i,1} - \dots - w_d x_{i,d}) x_{i,j} = 0$$

- **Vector of derivatives:**

$$\text{grad}_{\mathbf{w}}(J_n(\mathbf{w})) = \nabla_{\mathbf{w}}(J_n(\mathbf{w})) = -\frac{2}{n} \sum_{i=1}^n (y_i - \mathbf{w}^T \mathbf{x}_i) \mathbf{x}_i = \bar{\mathbf{0}}$$

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## Linear regression. Optimization.

- For the optimal set of parameters, derivatives of the error with respect to each parameter must be 0

$$J_n = \frac{1}{n} \sum_{i=1..n} (y_i - f(\mathbf{x}_i))^2 = \frac{1}{n} \sum_{i=1..n} (y_i - [w_0 + w_1 x^{(1)} + w_2 x^{(2)} + \dots + w_k x^{(k)}])^2$$

- $\text{grad}_{\mathbf{w}}(J_n(\mathbf{w})) = \bar{\mathbf{0}}$  defines a set of equations in  $\mathbf{w}$

$$\frac{\partial}{\partial w_0} J_n(w) = -\frac{2}{n} \sum_{i=1}^n [y_i - (w_0 + w_1 x^{(1)} + w_2 x^{(2)} + \dots + w_k x^{(k)})] = 0$$

$$\frac{\partial}{\partial w_1} J_n(w) = -\frac{2}{n} \sum_{i=1}^n [y_i - (w_0 + w_1 x^{(1)} + w_2 x^{(2)} + \dots + w_k x^{(k)})] x^{(1)} = 0$$

...

$$\frac{\partial}{\partial w_j} J_n(w) = -\frac{2}{n} \sum_{i=1}^n [y_i - (w_0 + w_1 x^{(1)} + w_2 x^{(2)} + \dots + w_k x^{(k)})] x^{(j)} = 0$$

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## Solving linear regression

$$\frac{\partial}{\partial w_j} J_n(\mathbf{w}) = -\frac{2}{n} \sum_{i=1}^n (y_i - w_0 x_{i,0} - w_1 x_{i,1} - \dots - w_d x_{i,d}) x_{i,j} = 0$$

By rearranging the terms we get a **system of linear equations** with  $d+1$  unknowns

$$\mathbf{A}\mathbf{w} = \mathbf{b}$$

$$\begin{aligned} w_0 \sum_{i=1}^n x_{i,0} 1 + w_1 \sum_{i=1}^n x_{i,1} 1 + \dots + w_j \sum_{i=1}^n x_{i,j} 1 + \dots + w_d \sum_{i=1}^n x_{i,d} 1 &= \sum_{i=1}^n y_i 1 \\ w_0 \sum_{i=1}^n x_{i,0} x_{i,1} + w_1 \sum_{i=1}^n x_{i,1} x_{i,1} + \dots + w_j \sum_{i=1}^n x_{i,j} x_{i,1} + \dots + w_d \sum_{i=1}^n x_{i,d} x_{i,1} &= \sum_{i=1}^n y_i x_{i,1} \\ &\vdots \\ w_0 \sum_{i=1}^n x_{i,0} x_{i,j} + w_1 \sum_{i=1}^n x_{i,1} x_{i,j} + \dots + w_j \sum_{i=1}^n x_{i,j} x_{i,j} + \dots + w_d \sum_{i=1}^n x_{i,d} x_{i,j} &= \sum_{i=1}^n y_i x_{i,j} \\ &\vdots \end{aligned}$$

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## Solving linear regression

- The optimal set of weights satisfies:

$$\nabla_{\mathbf{w}} (J_n(\mathbf{w})) = -\frac{2}{n} \sum_{i=1}^n (y_i - \mathbf{w}^T \mathbf{x}_i) \mathbf{x}_i = \mathbf{0}$$

Leads to a **system of linear equations (SLE)** with  $d+1$  unknowns of the form

$$\mathbf{A}\mathbf{w} = \mathbf{b}$$

$$w_0 \sum_{i=1}^n x_{i,0} x_{i,j} + w_1 \sum_{i=1}^n x_{i,1} x_{i,j} + \dots + w_j \sum_{i=1}^n x_{i,j} x_{i,j} + \dots + w_d \sum_{i=1}^n x_{i,d} x_{i,j} = \sum_{i=1}^n y_i x_{i,j}$$

### Solutions to SLE:

- e.g. matrix inversion (if the matrix is singular)

$$\mathbf{w} = \mathbf{A}^{-1} \mathbf{b}$$

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## Gradient descent solution

- There are other ways to solve the weight optimization problem in the linear regression model

$$J_n = \text{Error}(\mathbf{w}) = \frac{1}{n} \sum_{i=1 \dots n} (y_i - f(\mathbf{x}_i, \mathbf{w}))^2$$

- A simple technique:

- **Gradient descent**

**Idea:**

- Adjust weights in the direction that improves the Error
- The gradient tells us what is the right direction

$$\mathbf{w} \leftarrow \mathbf{w} - \alpha \nabla_{\mathbf{w}} \text{Error}_i(\mathbf{w})$$

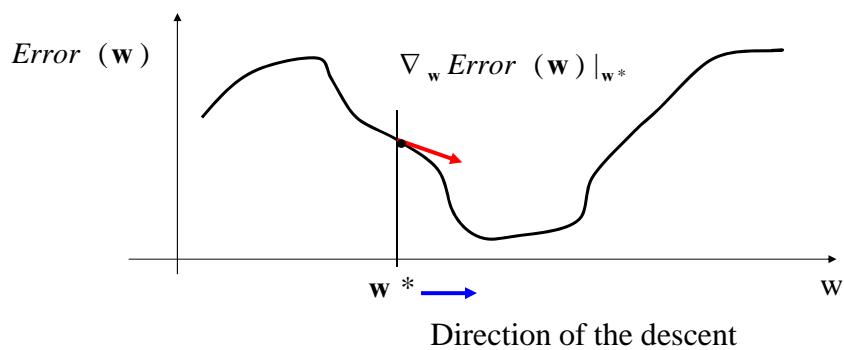
$\alpha > 0$  - a learning rate (scales the gradient changes)

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## Gradient descent method

- Descend using the gradient information



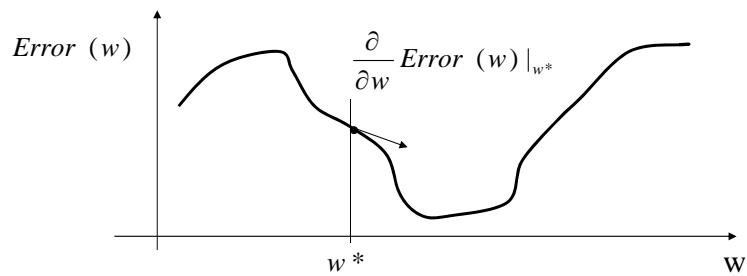
- Change the value of  $\mathbf{w}$  according to the gradient

$$\mathbf{w} \leftarrow \mathbf{w} - \alpha \nabla_{\mathbf{w}} \text{Error}_i(\mathbf{w})$$

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## Gradient descent method



- New value of the parameter

$$w_j \leftarrow w_j^* - \alpha \frac{\partial}{\partial w_j} \text{Error}(w) |_{w^*} \quad \text{For all } j$$

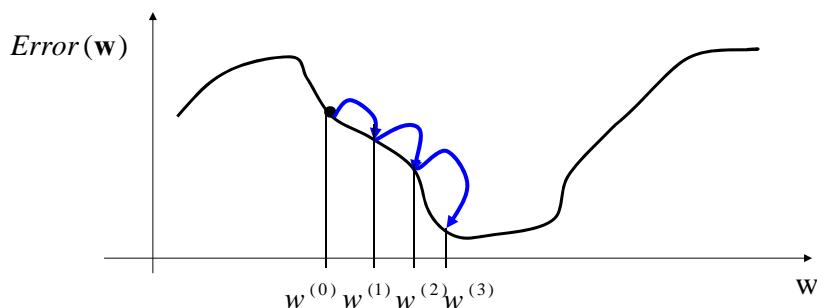
$\alpha > 0$  - a learning rate (scales the gradient changes)

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## Gradient descent method

- Iteratively converge to the optimum of the Error function



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## Batch vs Online regression algorithm

- The error function defined for the whole dataset  $D$ 
$$J_n = \text{Error}(\mathbf{w}) = \frac{1}{n} \sum_{i=1..n} (y_i - f(\mathbf{x}_i, \mathbf{w}))^2$$
- We say we are learning the model in **the batch mode**:
  - All examples are available at the time of learning
  - Weights are optimized with respect to all training examples
- An alternative is to learn the model in **the online mode**
  - Examples are arriving sequentially
  - Model weights are updated after every example
  - If needed examples seen can be forgotten

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## Online regression algorithm

- **Error function for the whole dataset  $D$** 
$$J_n = \text{Error}(\mathbf{w}) = \frac{1}{n} \sum_{i=1..n} (y_i - f(\mathbf{x}_i, \mathbf{w}))^2$$
- **Error for each example**  $D_i = \langle \mathbf{x}_i, y_i \rangle$ 
$$J_{\text{online}} = \text{Error}_i(\mathbf{w}) = \frac{1}{2} (y_i - f(\mathbf{x}_i, \mathbf{w}))^2$$
- **Change regression weights after every example according to the gradient:**
$$w_j \leftarrow w_j - \alpha \frac{\partial}{\partial w_j} \text{Error}_i(\mathbf{w})$$

**vector form:**  $\mathbf{w} \leftarrow \mathbf{w} - \alpha \nabla_{\mathbf{w}} \text{Error}_i(\mathbf{w})$

$\alpha > 0$  - Learning rate that depends on the number of updates

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## Gradient for on-line learning

Linear model

$$f(\mathbf{x}) = \mathbf{w}^T \mathbf{x}$$

On-line error

$$J_{\text{online}} = \text{Error}_i(\mathbf{w}) = \frac{1}{2}(y_i - f(\mathbf{x}_i, \mathbf{w}))^2$$

**On-line algorithm:** sequence of online updates

**(i)-th update for the linear model:**  $D_i = \langle \mathbf{x}_i, y_i \rangle$

**Vector form:**

$$\mathbf{w}^{(i)} \leftarrow \mathbf{w}^{(i-1)} - \alpha(i) \nabla_{\mathbf{w}} \text{Error}_i(\mathbf{w}) \Big|_{\mathbf{w}^{(i-1)}} = \mathbf{w}^{(i-1)} + \alpha(i)(y_i - f(\mathbf{x}_i, \mathbf{w}^{(i-1)}))\mathbf{x}_i$$

**j-th weight:**

$$w_j^{(i)} \leftarrow w_j^{(i-1)} - \alpha(i) \frac{\partial \text{Error}_i(\mathbf{w})}{\partial w_j} \Big|_{\mathbf{w}^{(i-1)}} = w_j^{(i-1)} + \alpha(i)(y_i - f(\mathbf{x}_i, \mathbf{w}^{(i-1)}))x_{i,j}$$

**Annealed learning rate:**  $\alpha(i) \approx \frac{1}{i}$

- Gradually rescales changes in weights

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## Online regression algorithm

**Online-linear-regression ( $D$ , number of iterations)**

**Initialize** weights  $\mathbf{w} = (w_0, w_1, w_2 \dots w_d)$

**for**  $i=1:1:$  number of iterations

**do**      **select** a data point  $D_i = (\mathbf{x}_i, y_i)$  from  $D$

**set**  $\alpha = 1/i$

**update** weight vector

$$\mathbf{w} \leftarrow \mathbf{w} + \alpha(y_i - f(\mathbf{x}_i, \mathbf{w}))\mathbf{x}_i$$

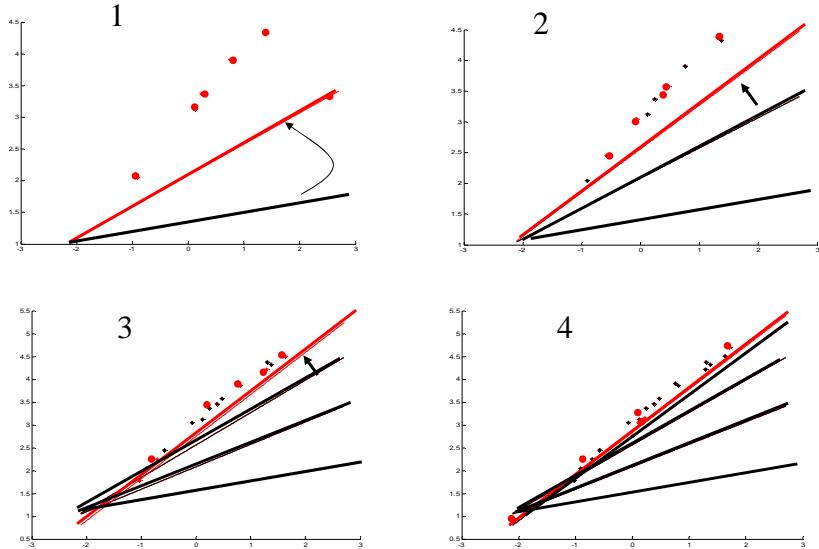
**end for**

**return** weights  $\mathbf{w}$

- **Advantages:** very easy to implement, continuous data streams

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## On-line learning. Example



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## Adaptive models

Linear model

$$f(\mathbf{x}) = \mathbf{w}^T \mathbf{x}$$

On-line error

$$J_{online} = Error_i(\mathbf{w}) = \frac{1}{2}(y_i - f(\mathbf{x}_i, \mathbf{w}))^2$$

### On-line algorithm:

- Sequence of online updates (one example at the time)
- Useful for continuous data streams

### Adaptive models:

- the underlying model is not stationary and can change over time
  - Example: seasonal changes
- On-line algorithm can be made adaptive by keeping the learning at some constant value  $\alpha(i) \approx c$

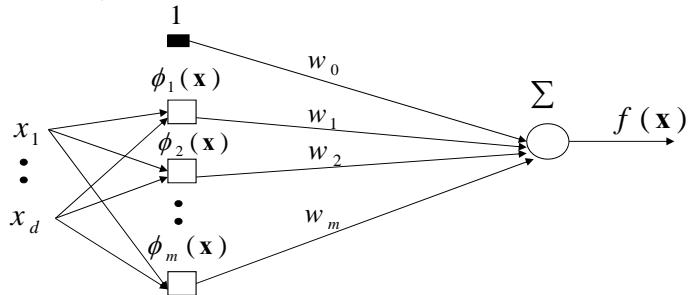
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## Extensions of simple linear model

Replace inputs to linear units with **feature (basis) functions** to model **nonlinearities**

$$f(\mathbf{x}) = w_0 + \sum_{j=1}^m w_j \phi_j(\mathbf{x})$$

$\phi_j(\mathbf{x})$  - an arbitrary function of  $\mathbf{x}$



**The same techniques as before to learn the weights**

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## Extensions of the linear model

- **Models linear in the parameters we want to fit**

$$f(\mathbf{x}) = w_0 + \sum_{k=1}^m w_k \phi_k(\mathbf{x})$$

$w_0, w_1 \dots w_m$  - parameters

$\phi_1(\mathbf{x}), \phi_2(\mathbf{x}) \dots \phi_m(\mathbf{x})$  - **feature or basis functions**

- **Basis functions examples:**

– a higher order polynomial, one-dimensional input  $\mathbf{x} = (x_1)$

$$\phi_1(x) = x \quad \phi_2(x) = x^2 \quad \phi_3(x) = x^3$$

– Multidimensional quadratic  $\mathbf{x} = (x_1, x_2)$

$$\phi_1(\mathbf{x}) = x_1 \quad \phi_2(\mathbf{x}) = x_1^2 \quad \phi_3(\mathbf{x}) = x_2 \quad \phi_4(\mathbf{x}) = x_2^2 \quad \phi_5(\mathbf{x}) = x_1 x_2$$

– Other types of basis functions

$$\phi_1(x) = \sin x \quad \phi_2(x) = \cos x$$

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## Extensions of the linear case

- **Error function**  $J_n(\mathbf{w}) = 1/n \sum_{i=1,\dots,n} (y_i - f(\mathbf{x}_i))^2$

Assume:  $\phi(\mathbf{x}_i) = (1, \phi_1(\mathbf{x}_i), \phi_2(\mathbf{x}_i), \dots, \phi_m(\mathbf{x}_i))$

$$\nabla_{\mathbf{w}} J_n(\mathbf{w}) = -\frac{2}{n} \sum_{i=1,\dots,n} (y_i - f(\mathbf{x}_i)) \phi(\mathbf{x}_i) = \bar{\mathbf{0}}$$

- Leads to a **system of  $m$  linear equations**

$$w_0 \sum_{i=1}^n \phi_j(\mathbf{x}_i) + \dots + w_j \sum_{i=1}^n \phi_j(\mathbf{x}_i) \phi_j(\mathbf{x}_i) + \dots + w_m \sum_{i=1}^n \phi_m(\mathbf{x}_i) \phi_j(\mathbf{x}_i) = \sum_{i=1}^n y_i \phi_j(\mathbf{x}_i)$$

- Can be solved exactly like the linear case

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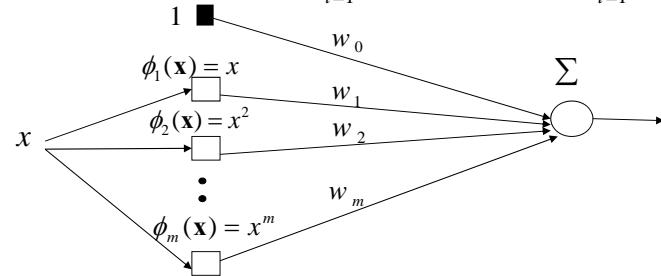
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## Example. Regression with polynomials.

### Regression with polynomials of degree $m$

- **Data points:** pairs of  $< x, y >$
- **Feature functions:**  $m$  feature functions  
 $\phi_i(x) = x^i \quad i = 1, 2, \dots, m$
- **Function to learn:**

$$f(x, \mathbf{w}) = w_0 + \sum_{i=1}^m w_i \phi_i(x) = w_0 + \sum_{i=1}^m w_i x^i$$




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## Example. Regression with polynomials.

**Example:** Regression with polynomials of degree m

$$f(x, \mathbf{w}) = w_0 + \sum_{i=1}^m w_i \phi_i(x) = w_0 + \sum_{i=1}^m w_i x^i$$

- **On line update** for  $\langle x, y \rangle$  pair

$$w_0 = w_0 + \alpha(y - f(\mathbf{x}, \mathbf{w}))$$

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$$w_j = w_j + \alpha(y - f(\mathbf{x}, \mathbf{w}))x^j$$

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## Learning with feature functions

**Function to learn:**

$$f(x, \mathbf{w}) = w_0 + \sum_{i=1}^k w_i \phi_i(x)$$

- **On line gradient update** for the  $\langle x, y \rangle$  pair

$$w_0 = w_0 + \alpha(y - f(\mathbf{x}, \mathbf{w}))$$

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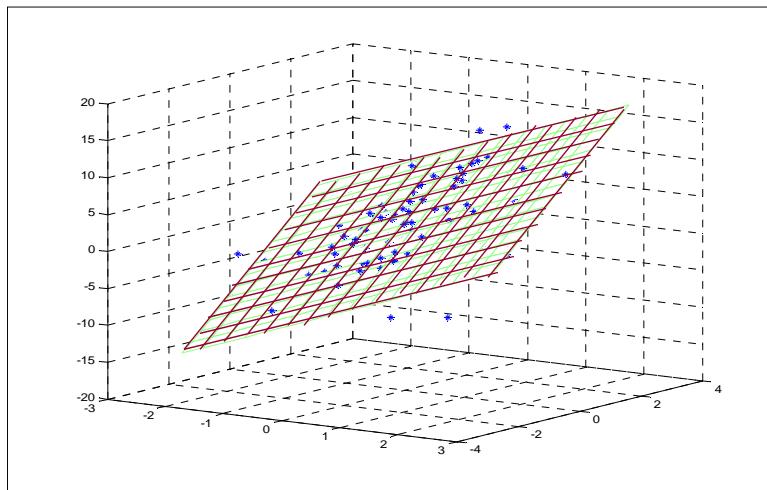
$$w_j = w_j + \alpha(y - f(\mathbf{x}, \mathbf{w}))\phi_j(\mathbf{x})$$

Gradient updates are of the same form as in the linear regression models

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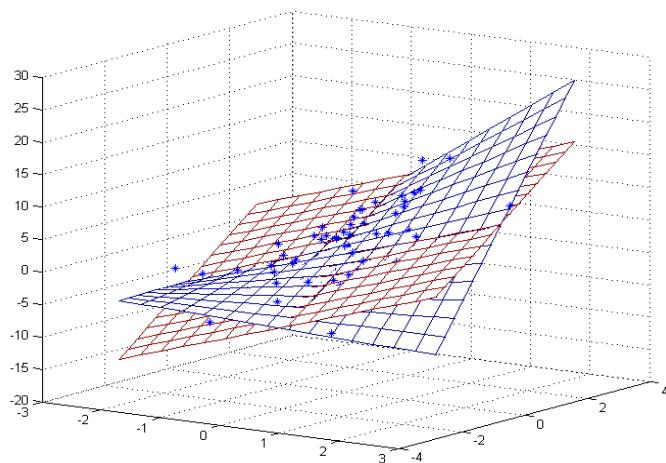
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## Extensions of the linear model example



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## Extensions of the linear model example



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## Binary classification

- **Two classes**  $Y = \{0,1\}$
- Our goal is to learn to classify correctly two types of examples
  - Class 0 – labeled as 0,
  - Class 1 – labeled as 1
- We would like to learn  $f : X \rightarrow \{0,1\}$
- **Zero-one error (loss) function**
$$Error_1(\mathbf{x}_i, y_i) = \begin{cases} 1 & f(\mathbf{x}_i, \mathbf{w}) \neq y_i \\ 0 & f(\mathbf{x}_i, \mathbf{w}) = y_i \end{cases}$$
- Error we would like to minimize:  $E_{(x,y)}(Error_1(\mathbf{x}, y))$
- **First step:** we need to devise a model of the function

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## Discriminant functions

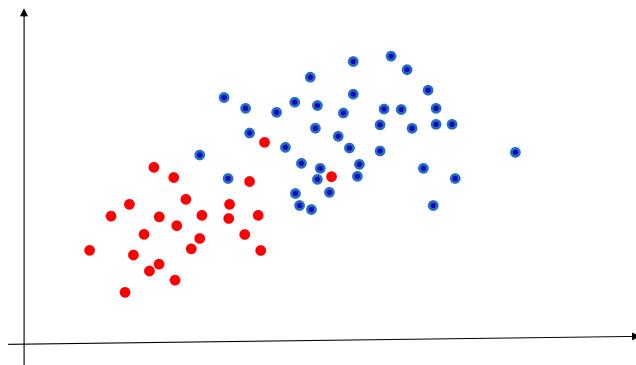
- One way to represent a **classifier** is by using
  - **Discriminant functions**
- **Works for binary and multi-way classification**
- **Idea:**
  - For every class  $i = 0, 1, \dots, k$  define a function  $g_i(\mathbf{x})$  mapping  $X \rightarrow \mathbb{R}$
  - When the decision on input  $\mathbf{x}$  should be made choose the class with the highest value of  $g_i(\mathbf{x})$
- So what happens with the input space? Assume a binary case.

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## Discriminant functions

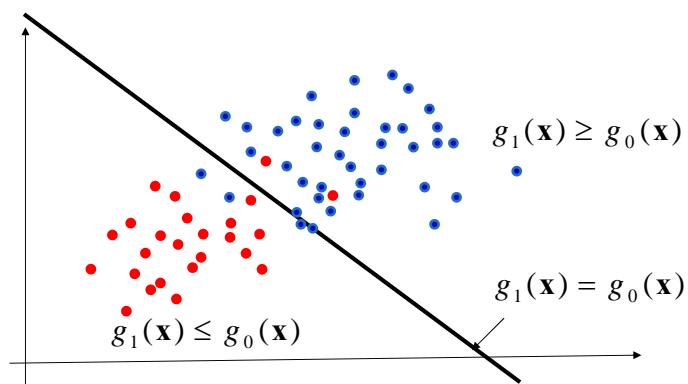
- Example: Two classes in 2-D



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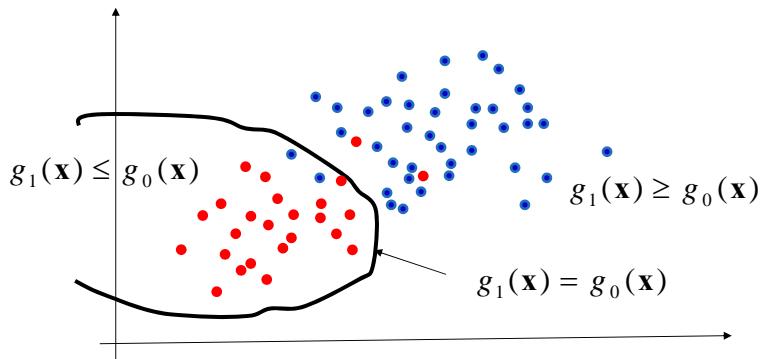
## Discriminant functions

- Discriminant functions  $g_0(\mathbf{x})$  and  $g_1(\mathbf{x})$  define the **decision boundary**



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## Quadratic decision boundary



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## Logistic regression model

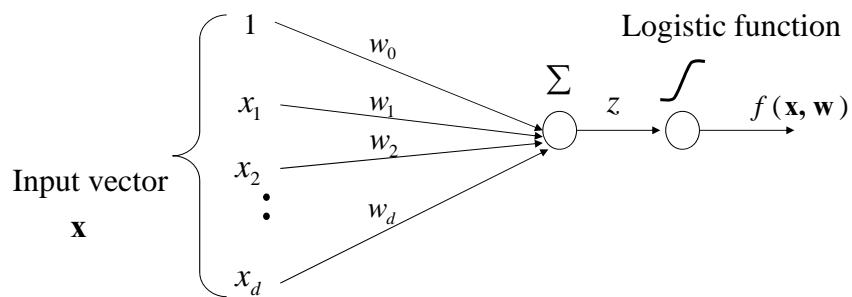
- Defines a linear decision boundary

- Discriminant functions:

$$g_1(\mathbf{x}) = g(\mathbf{w}^T \mathbf{x}) \quad g_0(\mathbf{x}) = 1 - g(\mathbf{w}^T \mathbf{x})$$

- where  $g(z) = 1/(1 + e^{-z})$  - is a logistic function

$$f(\mathbf{x}, \mathbf{w}) = g_1(\mathbf{w}^T \mathbf{x}) = g(\mathbf{w}^T \mathbf{x})$$



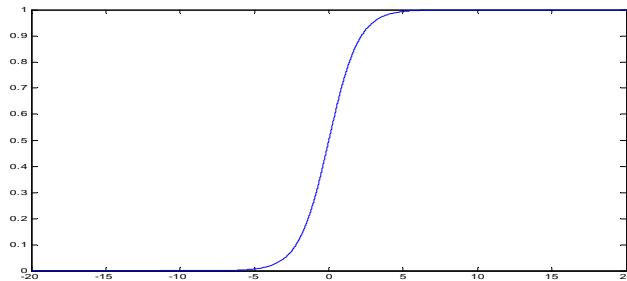
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## Logistic function

function

$$g(z) = \frac{1}{(1 + e^{-z})}$$

- Is also referred to as a **sigmoid function**
- Replaces the threshold function with smooth switching
- takes a real number and outputs the number in the interval [0,1]



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## Logistic regression model

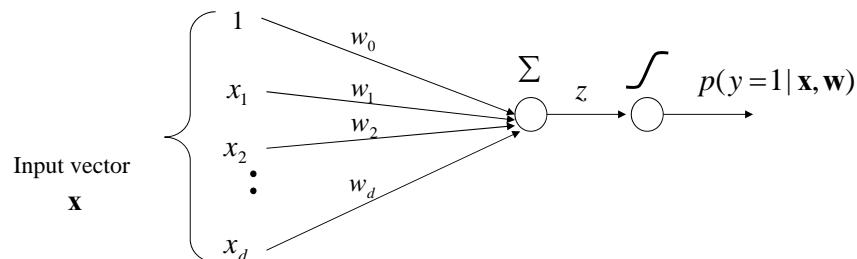
- **Discriminant functions:**

$$g_1(\mathbf{x}) = g(\mathbf{w}^T \mathbf{x}) \quad g_0(\mathbf{x}) = 1 - g(\mathbf{w}^T \mathbf{x})$$

- **Values of discriminant functions vary in [0,1]**

- **Probabilistic interpretation**

$$f(\mathbf{x}, \mathbf{w}) = p(y=1 | \mathbf{w}, \mathbf{x}) = g_1(\mathbf{x}) = g(\mathbf{w}^T \mathbf{x})$$



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## Logistic regression

- We learn **a probabilistic function**

$$f : X \rightarrow [0,1]$$

- where  $f$  describes the probability of class 1 given  $\mathbf{x}$

$$f(\mathbf{x}, \mathbf{w}) = g_1(\mathbf{w}^T \mathbf{x}) = p(y = 1 | \mathbf{x}, \mathbf{w})$$

**Note that:**

$$p(y = 0 | \mathbf{x}, \mathbf{w}) = 1 - p(y = 1 | \mathbf{x}, \mathbf{w})$$

- Transformation to binary class values:

If  $p(y = 1 | \mathbf{x}) \geq 1/2$  then choose **1**  
Else choose **0**

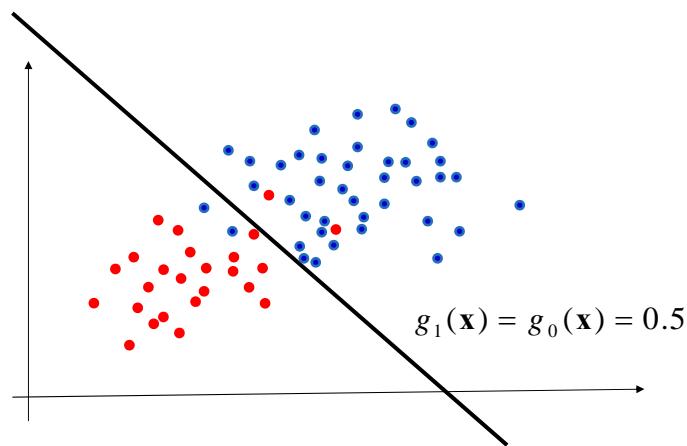
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## Logistic regression model. Decision boundary

- **Logistic Regression defines a linear decision boundary**

**Example:** 2 classes (blue and red points)



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## Logistic regression: parameter learning

### Likelihood of outputs

- Let

$$D_i = \langle \mathbf{x}_i, y_i \rangle \quad \mu_i = p(y_i = 1 | \mathbf{x}_i, \mathbf{w}) = g(z_i) = g(\mathbf{w}^T \mathbf{x})$$

- Then

$$L(D, \mathbf{w}) = \prod_{i=1}^n P(y = y_i | \mathbf{x}_i, \mathbf{w}) = \prod_{i=1}^n \mu_i^{y_i} (1 - \mu_i)^{1-y_i}$$

- Find weights  $\mathbf{w}$  that maximize the likelihood of outputs

– Apply the log-likelihood trick. The optimal weights are the same for both the likelihood and the log-likelihood

$$\begin{aligned} l(D, \mathbf{w}) &= \log \prod_{i=1}^n \mu_i^{y_i} (1 - \mu_i)^{1-y_i} = \sum_{i=1}^n \log \mu_i^{y_i} (1 - \mu_i)^{1-y_i} = \\ &= \sum_{i=1}^n y_i \log \mu_i + (1 - y_i) \log(1 - \mu_i) \end{aligned}$$

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## Logistic regression: parameter learning

- Log likelihood

$$l(D, \mathbf{w}) = \sum_{i=1}^n y_i \log \mu_i + (1 - y_i) \log(1 - \mu_i)$$

- Derivatives of the loglikelihood

$$\begin{aligned} -\frac{\partial}{\partial w_j} l(D, \mathbf{w}) &= \sum_{i=1}^n -x_{i,j} (y_i - g(z_i)) && \text{Nonlinear in weights !!} \\ \nabla_{\mathbf{w}} -l(D, \mathbf{w}) &= \sum_{i=1}^n -\mathbf{x}_i (y_i - g(\mathbf{w}^T \mathbf{x}_i)) = \sum_{i=1}^n -\mathbf{x}_i (y_i - f(\mathbf{w}, \mathbf{x}_i)) \end{aligned}$$

- Gradient descent:  $\mathbf{w}^{(k)} \leftarrow \mathbf{w}^{(k-1)} - \alpha(k) \nabla_{\mathbf{w}} [-l(D, \mathbf{w})] \Big|_{\mathbf{w}^{(k-1)}}$

### k-th update

$$\mathbf{w}^{(k)} \leftarrow \mathbf{w}^{(k-1)} + \alpha(k) \sum_{i=1}^n [y_i - f(\mathbf{w}^{(k-1)}, \mathbf{x}_i)] \mathbf{x}_i$$

---

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## Logistic regression. Online gradient descent

- **On-line component of the loglikelihood**

$$- J_{\text{online}}(D_i, \mathbf{w}) = y_i \log \mu_i + (1 - y_i) \log(1 - \mu_i)$$

- **On-line learning update for weight  $\mathbf{w}$**   $J_{\text{online}}(D_k, \mathbf{w})$

$$\mathbf{w}^{(k)} \leftarrow \mathbf{w}^{(k-1)} - \alpha(k) \nabla_{\mathbf{w}} [J_{\text{online}}(D_k, \mathbf{w})] |_{\mathbf{w}^{(k-1)}}$$

- **Online update for the logistic regression for k-th example**

$$D_k = \langle \mathbf{x}_k, y_k \rangle$$

$$\mathbf{w}^{(k)} \leftarrow \mathbf{w}^{(k-1)} + \alpha(k)[y_k - f(\mathbf{w}^{(k-1)}, \mathbf{x}_k)]\mathbf{x}_k$$

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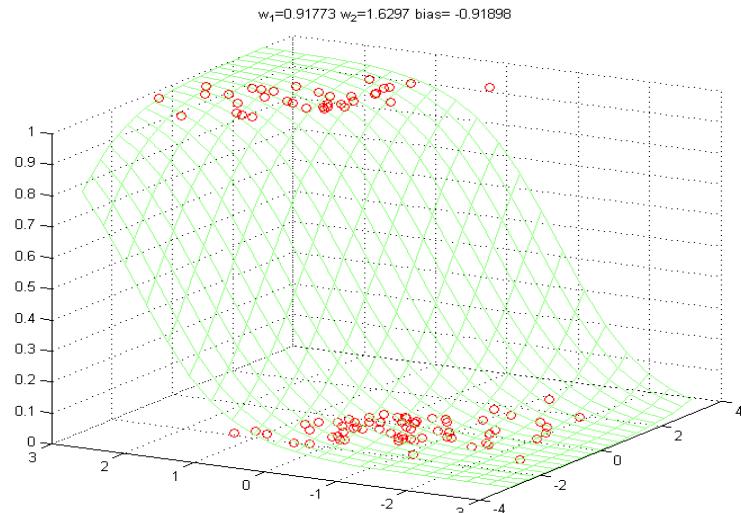
## Online logistic regression algorithm

**Online-logistic-regression** ( $D$ , number of iterations)

```
initialize weights  $\mathbf{w} = (w_0, w_1, w_2 \dots w_d)$ 
for  $i=1:1:$  number of iterations
    do      select a data point  $D_i = \langle \mathbf{x}_i, y_i \rangle$  from  $D$ 
            set  $\alpha = 1/i$ 
            update weights (in parallel)
             $\mathbf{w} \leftarrow \mathbf{w} + \alpha(i)[y_i - f(\mathbf{w}, \mathbf{x}_i)]\mathbf{x}_i$ 
    end for
return weights  $\mathbf{w}$ 
```

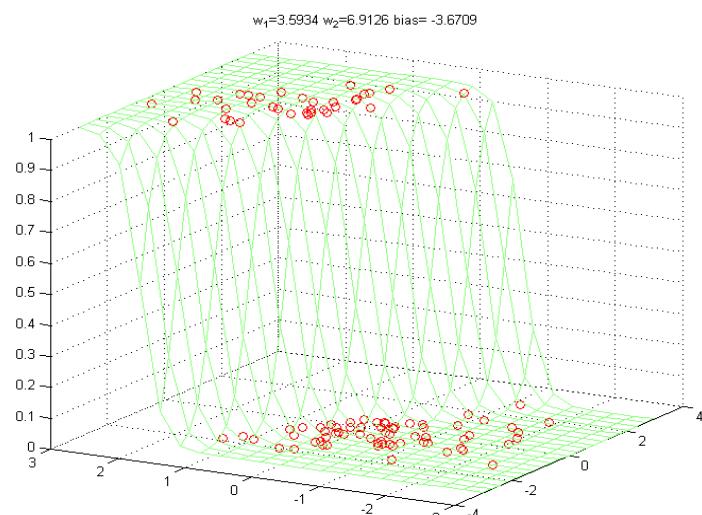
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## Online algorithm. Example.



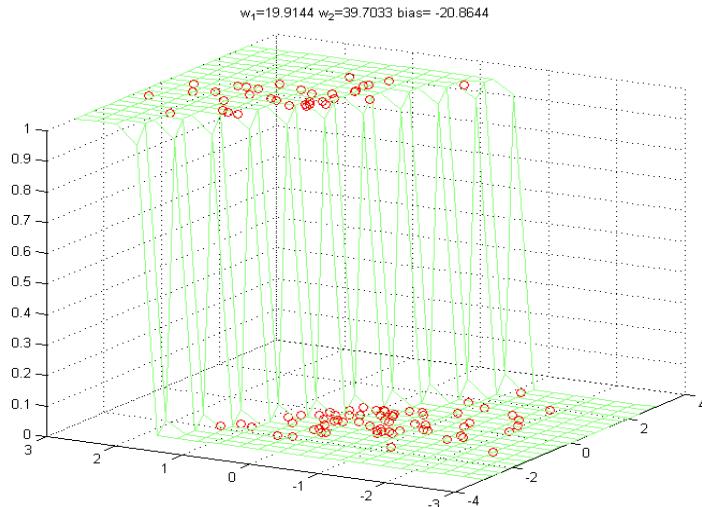
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## Online algorithm. Example.



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## Online algorithm. Example.



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## Appendix: Derivation of the gradient

- **Log likelihood**  $l(D, \mathbf{w}) = \sum_{i=1}^n y_i \log \mu_i + (1 - y_i) \log(1 - \mu_i)$

- **Derivatives of the loglikelihood**

$$\frac{\partial}{\partial w_j} l(D, \mathbf{w}) = \sum_{i=1}^n \frac{\partial}{\partial z_i} [y_i \log \mu_i + (1 - y_i) \log(1 - \mu_i)] \frac{\partial z_i}{\partial w_j}$$

**Derivative of a logistic function**

$$\frac{\partial z_i}{\partial w_j} = x_{i,j} \quad \frac{\partial g(z_i)}{\partial z_i} = g(z_i)(1 - g(z_i))$$

$$\begin{aligned} \frac{\partial}{\partial z_i} [y_i \log \mu_i + (1 - y_i) \log(1 - \mu_i)] &= y_i \frac{1}{g(z_i)} \frac{\partial g(z_i)}{\partial z_i} + (1 - y_i) \frac{-1}{1 - g(z_i)} \frac{\partial g(z_i)}{\partial z_i} \\ &= y_i(1 - g(z_i)) + (1 - y_i)(-g(z_i)) = y_i - g(z_i) \end{aligned}$$

$$\nabla_{\mathbf{w}} l(D, \mathbf{w}) = \sum_{i=1}^n -\mathbf{x}_i(y_i - g(\mathbf{w}^T \mathbf{x}_i)) = \sum_{i=1}^n -\mathbf{x}_i(y_i - f(\mathbf{w}, \mathbf{x}_i))$$

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