CS 1571 Introduction to AI Lecture 20

Bayesian belief networks

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Modeling uncertainty with probabilities

- Defining the **full joint distribution** makes it possible to represent and reason with uncertainty in a uniform way
- We are able to handle an arbitrary inference problem

Problems:

- **Space complexity.** To store a full joint distribution we need to remember $O(d^n)$ numbers.
 - n number of random variables, d number of values
- Inference (time) complexity. To compute some queries requires $O(d^n)$ steps.
- Acquisition problem. Who is going to define all of the probability entries?

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Bayesian belief networks (BBNs)

Bayesian belief networks.

- Represent the full joint distribution over the variables more compactly with a **smaller number of parameters**.
- Take advantage of **conditional and marginal independences** among random variables
- A and B are independent

$$P(A,B) = P(A)P(B)$$

A and B are conditionally independent given C

$$P(A, B \mid C) = P(A \mid C)P(B \mid C)$$

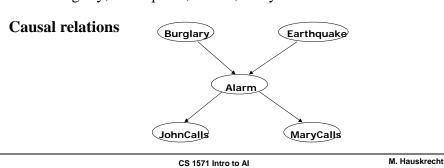
$$P(A \mid C, B) = P(A \mid C)$$

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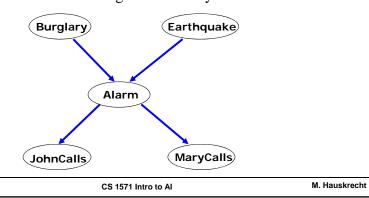
Alarm system example

- Assume your house has an alarm system against burglary.
 You live in the seismically active area and the alarm system
 can get occasionally set off by an earthquake. You have two
 neighbors, Mary and John, who do not know each other. If
 they hear the alarm they call you, but this is not guaranteed.
- We want to represent the probability distribution of events:
 - Burglary, Earthquake, Alarm, Mary calls and John calls



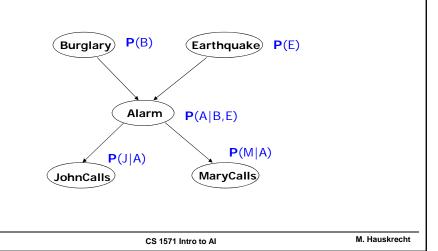
Bayesian belief network

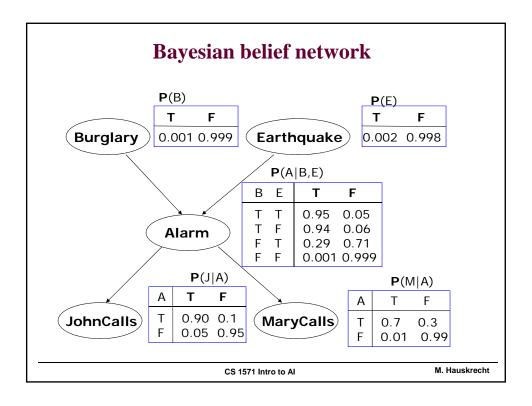
- 1. Directed acyclic graph
 - **Nodes** = random variables Burglary, Earthquake, Alarm, Mary calls and John calls
 - **Links** = direct (causal) dependencies between variables. The chance of Alarm is influenced by Earthquake, The chance of John calling is affected by the Alarm



Bayesian belief network

- 2. Local conditional distributions
 - relate variables and their parents



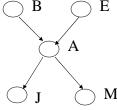


Bayesian belief networks (general)

Two components: $B = (S, \Theta_s)$

• Directed acyclic graph

- Nodes correspond to random variables
- (Missing) links encode independences



Parameters

- Local conditional probability distributions for every variable-parent configuration

$$\mathbf{P}(X_i \mid pa(X_i))$$

Where:

$$pa(X_i)$$
 - stand for parents of X_i

\bigcirc B	\supset F	3
	A	
\bigcirc J		M

В	Е	T	F
T T F F	\bot \vdash \vdash \vdash	0.94	0.05 0.06 0.71 0.999

P(A|B,E)

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Full joint distribution in BBNs

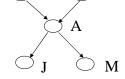
Full joint distribution is defined in terms of local conditional distributions (obtained via the chain rule):

$$\mathbf{P}(X_{1}, X_{2}, ..., X_{n}) = \prod_{i=1,..n} \mathbf{P}(X_{i} \mid pa(X_{i}))$$

Example:

Assume the following assignment of values to random variables

$$B = T, E = T, A = T, J = T, M = F$$



Then its probability is:

$$P(B=T, E=T, A=T, J=T, M=F) =$$

$$P(B=T)P(E=T)P(A=T|B=T,E=T)P(J=T|A=T)P(M=F|A=T)$$

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Bayesian belief networks (BBNs)

Bayesian belief networks

- Represent the full joint distribution over the variables more compactly using the product of local conditionals.
- But how did we get to local parameterizations?

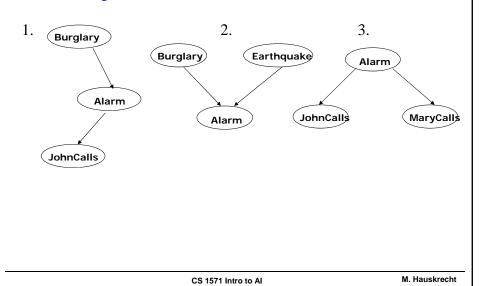
Answer:

- Chain rule +
- Graphical structure encodes conditional and marginal independences among random variables
- A and B are independent P(A,B) = P(A)P(B)
- A and B are conditionally independent given C $P(A \mid C, B) = P(A \mid C) \qquad P(A, B \mid C) = P(A \mid C)P(B \mid C)$
- The graph structure implies the decomposition !!!

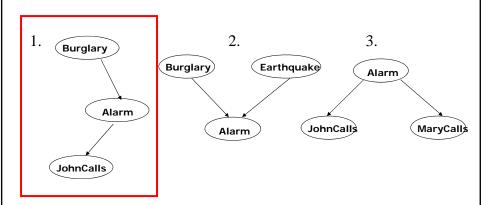
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Independences in BBNs

3 basic independence structures:



Independences in BBNs



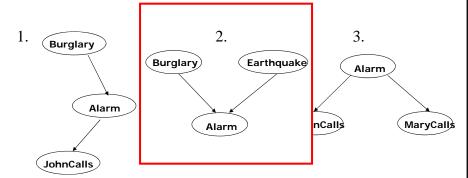
1. JohnCalls is independent of Burglary given Alarm

$$P(J \mid A, B) = P(J \mid A)$$

$$P(J, B \mid A) = P(J \mid A)P(B \mid A)$$

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Independences in BBNs



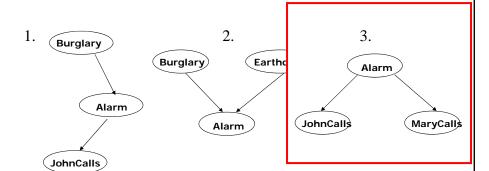
2. Burglary **is independent** of Earthquake (not knowing Alarm) Burglary and Earthquake **become dependent** given Alarm!!

$$P(B,E) = P(B)P(E)$$

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Independences in BBNs



3. MaryCalls is independent of JohnCalls given Alarm

$$P(J \mid A, M) = P(J \mid A)$$

$$P(J, M \mid A) = P(J \mid A)P(M \mid A)$$

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Independences in BBN

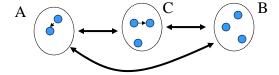
- BBN distribution models many conditional independence relations among distant variables and sets of variables
- These are defined in terms of the graphical criterion called dseparation
- D-separation and independence
 - Let X,Y and Z be three sets of nodes
 - If X and Y are d-separated by Z, then X and Y are conditionally independent given Z
- D-separation:
 - A is d-separated from B given C if every undirected path between them is blocked with C
- · Path blocking
 - 3 cases that expand on three basic independence structures

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Undirected path blocking

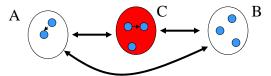
A is d-separated from B given C if every undirected path between them is **blocked**



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Undirected path blocking

A is d-separated from B given C if every undirected path between them is **blocked**

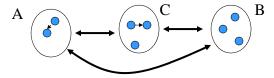


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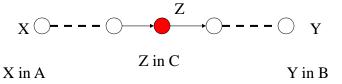
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Undirected path blocking

A is d-separated from B given C if every undirected path between them is **blocked**



• 1. Path blocking with a linear substructure

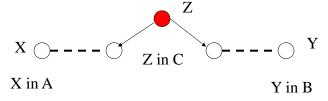


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Undirected path blocking

A is d-separated from B given C if every undirected path between them is **blocked**

• 2. Path blocking with the wedge substructure



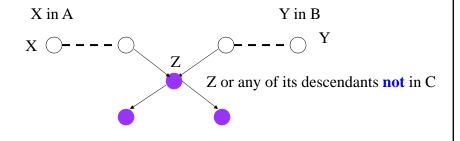
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Undirected path blocking

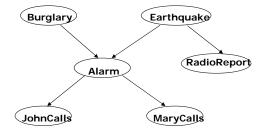
A is d-separated from B given C if every undirected path between them is **blocked**

• 3. Path blocking with the vee substructure



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Independences in BBNs



- Earthquake and Burglary are independent given MaryCalls **F**
- Burglary and MaryCalls are independent (not knowing Alarm) F
- Burglary and RadioReport are independent given Earthquake T
- Burglary and RadioReport are independent given MaryCalls **F**

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Bayesian belief networks (BBNs)

Bayesian belief networks

- Represents the full joint distribution over the variables more compactly using the product of local conditionals.
- So how did we get to local parameterizations?

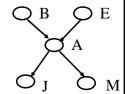
$$\mathbf{P}(X_1, X_2, ..., X_n) = \prod_{i=1...n} \mathbf{P}(X_i \mid pa(X_i))$$

 The decomposition is implied by the set of independences encoded in the belief network.

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Full joint distribution in BBNs

Rewrite the full joint probability using the product rule:



$$P(B=T, E=T, A=T, J=T, M=F) =$$

$$= P(J = T | B = T, E = T, A = T, M = F)P(B = T, E = T, A = T, M = F)$$

$$= P(J = T | A = T)P(B = T, E = T, A = T, M = F)$$

$$P(M = F | B = T, E = T, A = T)P(B = T, E = T, A = T)$$

$$P(M = F | A = T)P(B = T, E = T, A = T)$$

$$P(A = T | B = T, E = T)P(B = T, E = T)$$

$$P(B = T)P(E = T)$$

$$= P(J = T | A = T)P(M = F | A = T)P(A = T | B = T, E = T)P(B = T)P(E = T)$$

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Parameter complexity problem

• In the BBN the **full joint distribution** is defined as:

$$\mathbf{P}(X_1, X_2, ..., X_n) = \prod_{i=1,...n} \mathbf{P}(X_i \mid pa(X_i))$$

• What did we save?

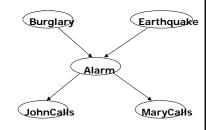
Alarm example: 5 binary (True, False) variables

of parameters of the full joint:

$$2^5 = 32$$

One parameter is for free:

$$2^5 - 1 = 31$$



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Parameter complexity problem

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Alarm example: 5 binary (True, False) variables

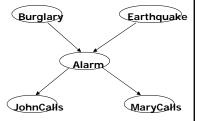
of parameters of the full joint:

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of parameters of the BBN: ?

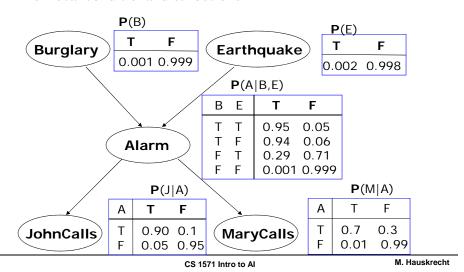


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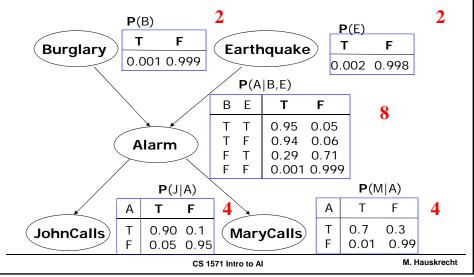
Bayesian belief network.

• In the BBN the **full joint distribution** is expressed using a set of local conditional distributions



Bayesian belief network.

• In the BBN the **full joint distribution** is expressed using a set of local conditional distributions



Parameter complexity problem

• In the BBN the **full joint distribution** is defined as:

$$\mathbf{P}(X_1, X_2, ..., X_n) = \prod_{i=1,...n} \mathbf{P}(X_i \mid pa(X_i))$$

• What did we save?

Alarm example: 5 binary (True, False) variables

of parameters of the full joint:

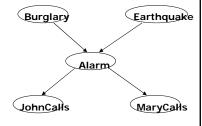
$$2^5 = 32$$

One parameter is for free:

$$2^5 - 1 = 31$$

of parameters of the BBN:

$$2^3 + 2(2^2) + 2(2) = 20$$



One parameter in every conditional is for free:

$$2^2 + 2(2) + 2(1) = 10$$

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Model acquisition problem

The structure of the BBN

- typically reflects causal relations
 (BBNs are also sometime referred to as causal networks)
- Causal structure is intuitive in many applications domain and it is relatively easy to define to the domain expert

Probability parameters of BBN

- are conditional distributions relating random variables and their parents
- Complexity is much smaller than the full joint
- It is much easier to obtain such probabilities from the expert or learn them automatically from data

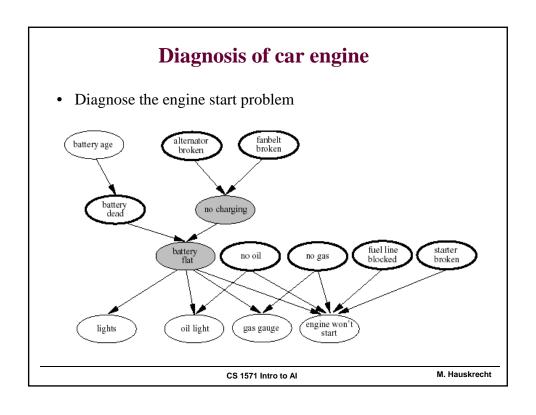
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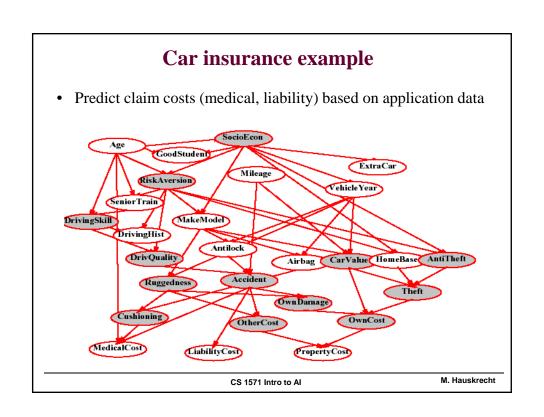
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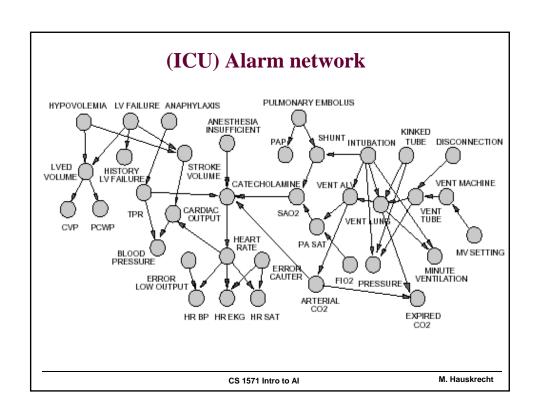
BBNs built in practice

- In various areas:
 - Intelligent user interfaces (Microsoft)
 - Troubleshooting, diagnosis of a technical device
 - Medical diagnosis:
 - Pathfinder (Intellipath)
 - CPSC
 - Munin
 - QMR-DT
 - Collaborative filtering
 - Military applications
 - Business and finance
 - Insurance, credit applications

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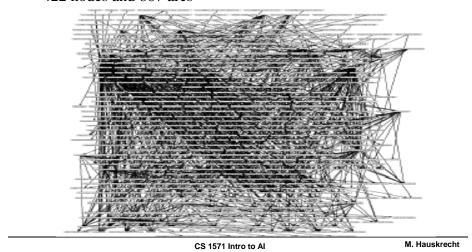








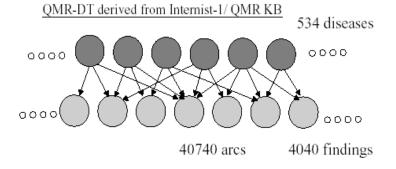
- Computer-based Patient Case Simulation system (CPCS-PM) developed by Parker and Miller (University of Pittsburgh)
- 422 nodes and 867 arcs



QMR-DT

- Medical diagnosis in internal medicine
- Based on QMR system built at U Pittsburgh

Bipartite network of disease/findings relations

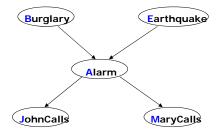


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Inference in Bayesian network

- Bad news:
 - Exact inference problem in BBNs is NP-hard (Cooper)
 - Approximate inference is NP-hard (Dagum, Luby)
- But very often we can achieve significant improvements
- Assume our Alarm network



• Assume we want to compute: P(J = T)

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Computing: P(J = T)

Approach 1. Blind approach.

- Sum out all un-instantiated variables from the full joint,
- express the joint distribution as a product of conditionals

$$P(J=T)=$$

$$= \sum_{b \in T} \sum_{F} \sum_{o \in T} \sum_{F} \sum_{a \in T} P(B = b, E = e, A = a, J = T, M = m)$$

$$= \sum_{b \in T, F} \sum_{a \in T, F} \sum_{a \in T, F} P(J = T \mid A = a) P(M = m \mid A = a) P(A = a \mid B = b, E = e) P(B = b) P(E = e)$$

Computational cost:

Number of additions: 15

Number of products: 16*4=64

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Inference in Bayesian networks

Approach 2. Interleave sums and products

 Combines sums and product in a smart way (multiplications by constants can be taken out of the sum)

$$\sum_{\{x\}} af(x) = a \sum_{\{x\}} f(x)$$

$$P(J=T)=$$

$$= \sum_{b \in T, F} \sum_{a \in T, F} \sum_{a \in T, F} P(J = T \mid A = a) P(M = m \mid A = a) P(A = a \mid B = b, E = e) P(B = b) P(E = e)$$

$$= \sum_{b \in T, F} \sum_{a \in T, F} P(J = T \mid A = a) P(M = m \mid A = a) P(B = b) \left[\sum_{e \in T, F} P(A = a \mid B = b, E = e) P(E = e) \right]$$

$$= \sum_{a \in T, F} P(J = T \mid A = a) \left[\sum_{m \in T, F} P(M = m \mid A = a) \right] \left[\sum_{b \in T, F} P(B = b) \left[\sum_{e \in T, F} P(A = a \mid B = b, E = e) P(E = e) \right] \right]$$

$$= \sum_{a \in T, F} P(J = T \mid A = a) \left[\sum_{m \in T, F} P(M = m \mid A = a) \right] \left[\sum_{b \in T, F} P(B = b) \left[\sum_{e \in T, F} P(A = a \mid B = b, E = e) P(E = e) \right] \right]$$

Computational cost: ?

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Approach 2. Interleave sums and products

• Combines sums and product in a smart way (multiplications by constants can be taken out of the sum)

$$= \sum_{a \in T, F} P(J = T \mid A = a) \left[\sum_{m \in T, F} P(M = m \mid A = a) \right] \left[\sum_{b \in T, F} P(B = b) \left[\sum_{e \in T, F} P(A = a \mid B = b, E = e) P(E = e) \right] \right]$$

Computational cost:

Number of additions: ?

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$$2*1$$

Computational cost:

Number of additions: ?

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$$= \sum_{a \in T, F} P(J = T \mid A = a) \left[\sum_{m \in T, F} P(M = m \mid A = a) \right] \left[\sum_{b \in T, F} P(B = b) \left[\sum_{e \in T, F} P(A = a \mid B = b, E = e) P(E = e) \right] \right]$$

$$2*2*1$$

Computational cost:

Number of additions: ?

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$$2*2*1$$

Computational cost:

Number of additions: ?

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Computational cost:

Number of additions: ?

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$$2*1$$

$$2*2*1$$

Computational cost:

Number of additions: 1+2*[1+1+2*1]=9

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Approach 2. Interleave sums and products

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$$= \sum_{a \in T, F} P(J = T \mid A = a) \left[\sum_{m \in T, F} P(M = m \mid A = a) \right] \left[\sum_{b \in T, F} P(B = b) \left[\sum_{e \in T, F} P(A = a \mid B = b, E = e) P(E = e) \right] \right]$$

Computational cost:

Number of products: ?

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Approach 2. Interleave sums and products

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$$2 * 2 * 2 * 1$$

Computational cost:

Number of products: ?

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Approach 2. Interleave sums and products

• Combines sums and product in a smart way (multiplications by constants can be taken out of the sum)

$$= \sum_{a \in T, F} P(J = T \mid A = a) \left[\sum_{m \in T, F} P(M = m \mid A = a) \right] \left[\sum_{b \in T, F} P(B = b) \left[\sum_{e \in T, F} P(A = a \mid B = b, E = e) P(E = e) \right] \right]$$

$$2*2$$

$$2*2*1$$

$$2*2*2*1$$

Computational cost:

Number of products: 2*[2+2*(1+2*1)]=16

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 Combines sums and product in a smart way (multiplications by constants can be taken out of the sum)

$$P(J=T)=$$

$$= \sum_{b \in T, F} \sum_{a \in T, F} \sum_{a \in T, F} \sum_{m \in T, F} P(J = T \mid A = a) P(M = m \mid A = a) P(A = a \mid B = b, E = e) P(B = b) P(E = e) P(E =$$

$$= \sum_{b \in T, F} \sum_{a \in T, F} \sum_{m \in T, F} P(J = T \mid A = a) P(M = m \mid A = a) P(B = b) \left[\sum_{e \in T, F} P(A = a \mid B = b, E = e) P(E = e) \right]$$

$$= \sum_{b \in T, F} \sum_{e \in T, F} \sum_{a \in T, F} \sum_{m \in T, F} P(J = T \mid A = a) P(M = m \mid A = a) P(A = a \mid B = b, E = e) P(B = b) P(E = e)$$

$$= \sum_{b \in T, F} \sum_{a \in T, F} \sum_{m \in T, F} P(J = T \mid A = a) P(M = m \mid A = a) P(B = b) \left[\sum_{e \in T, F} P(A = a \mid B = b, E = e) P(E = e) \right]$$

$$= \sum_{a \in T, F} P(J = T \mid A = a) \left[\sum_{m \in T, F} P(M = m \mid A = a) \right] \left[\sum_{b \in T, F} P(B = b) \left[\sum_{e \in T, F} P(A = a \mid B = b, E = e) P(E = e) \right]$$

Number of additions: 1+2*[1+1+2*1]=9

Number of products: 2*[2+2*(1+2*1)]=16

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Variable elimination

Variable elimination:

- Similar idea but interleave sum and products one variable at the time during inference
- E.g. Query P(J=T) requires to eliminate A,B,E,M and this can be done in different order

$$P(J = T) =$$

$$= \sum_{b \in T, F} \sum_{a \in T, F} \sum_{a \in T, F} P(J = T \mid A = a) P(M = m \mid A = a) P(A = a \mid B = b, E = e) P(B = b) P(E = e)$$

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M. Hauskrecht

Variable elimination

Assume order: M, E, B,A to calculate P(J = T)

$$= \sum_{b \in T, F} \sum_{a \in T, F} \sum_{a \in T, F} P(J = T \mid A = a) P(M = m \mid A = a) P(A = a \mid B = b, E = e) P(B = b) P(E = e)$$

$$= \sum_{b \in T, F} \sum_{e \in T, F} \sum_{a \in T, F} P(J = T \mid A = a) P(A = a \mid B = b, E = e) P(B = b) P(E = e) \left[\sum_{m \in T, F} P(M = m \mid A = a) \right]$$

$$= \sum_{b \in T, F} \sum_{e \in T, F} \sum_{a \in T, F} P(J = T \mid A = a) P(A = a \mid B = b, E = e) P(B = b) P(E = e) \quad 1$$

$$= \sum_{a \in T, F} \sum_{b \in T, F} P(J = T \mid A = a) P(B = b) \left[\sum_{e \in T, F} P(A = a \mid B = b, E = e) P(E = e) \right]$$

$$= \sum_{b \in T, F} \sum_{a \in T, F} \sum_{a \in T, F} P(J = T \mid A = a) P(A = a \mid B = b, E = e) P(B = b) P(E = e) \quad 1$$

$$= \sum_{a \in T, F} \sum_{b \in T, F} P(J = T \mid A = a) P(B = b) \left[\sum_{e \in T, F} P(A = a \mid B = b, E = e) P(E = e) \right]$$

$$= \sum_{x \in T} \sum_{b \in T} P(J = T \mid A = a) P(B = b) \tau_1(A = a, B = b)$$

$$= \sum_{a \in T, F} \sum_{b \in T, F} P(J = T \mid A = a) P(B = b) \tau_1(A = a, B = b)$$

$$= \sum_{a \in T, F} P(J = T \mid A = a) \left[\sum_{b \in T, F} P(B = b) \tau_1(A = a, B = b) \right]$$

$$= \sum_{a \in T, F} P(J = T \mid A = a) \quad \tau_2(A = a) \quad = P(J = T)$$

$$= \sum_{a \in T} P(J = T \mid A = a) \quad \tau_2(A = a) \quad = \quad P(J = T)$$

- Exact inference algorithms:
- **─** Variable elimination

Book

- **Recursive decomposition** (Cooper, Darwiche)
- Symbolic inference (D'Ambrosio)
- Belief propagation algorithm (Pearl)

Book

- Clustering and joint tree approach (Lauritzen, Spiegelhalter)
- Arc reversal (Olmsted, Schachter)
- Approximate inference algorithms:
- Pook
- Monte Carlo methods:
 - Forward sampling, Likelihood sampling
- Variational methods

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