### **Method Optimizations**



### **Method Inlining**

### Benefits:

- Less dynamic instructions
  - Call site removed, prologue and epilogue code eliminated
- Smaller dynamic memory needs since the activation record is eliminated
- Removal of control flow transfer helps eliminate branch penalties and improves instruction cache locality
- After inlining is performed, more code is available to the optimizer to improve

### Disadvantages:

- Static code size increase is likely
- Code growth can impact instruction cache performance
- May increase register pressure

### **Method Inlining**

In languages like C++, there is a keyword  $\mbox{inline}$  that hints to the compiler that a method should be inlined during compilation.

In C, this is one of the benefits of using a parameterized #define macro.

In OOPLs, we often have very small methods (usually acting as accessors and mutators) that can be inlined.

Inlining is not always the right thing to do, and so the compiler must use heuristics to decide to apply it or not.

Unknown depth recursion makes inlining difficult.

### **Tail Recursion Elimination**

A tail call is a function call site that appears as the last statement in a function.

Example:

```
int factorial(int x) {
    if(x < 2) return 1;
    return x * fact(x-1);
}</pre>
```

Tail calls can be implemented without adding a new activation record to the stack.

The activation record of the original call is reused, substituting in the new parameter values as appropriate. The tail call is then replaced with a jump to the beginning of the function.

### **Optimization Order**

# A: Source Code or High-Level IR

- Scalar replacement of array references
- Data-cache optimization

## **B: Medium-Level IR**

- Procedure integration
- Tail-call optimization
- Scalar replacement of aggregatesSparse conditional constant propagation
- Sparse conditional constant propagation
   Interprocedural constant propagation
- Procedure specialization and cloning

### C:Medium/Low-level IR

- Global value numbering
- Local and global copy propagationSparse conditional constant propagation
- Dead code elimination
- Local and global common subexpression elimination
- Loop-invariant code motion
- Partial redundancy elimination
- Code hoisting
- · Induction-variable strength reduction
- Linear-function test replacement
- Induction-variable removal
- Unnecessary bounds-checking eliminationControl-flow optimizations

- D: Low-level IR/Machine code
- Inline expansionLeaf routine optimization
- Shrink wrapping
- Machine idioms
- Tail merging
- · Branch optimizations and conditional moves
- Dead-code elimination
- · Software pipelining: loop unrolling, variable expansion, etc.
- · Basic-block scheduling
- Register allocation
- Intraprocedural I-cache optimization
- Instruction prefetching
- Data prefetchingBranch prediction

### Each Step

After A, B, C, and D,

- Constant folding
- Algebraic simplification

# E: Link Time Optimization

- Interprocedural register allocation
- Aggregation of global referencesInterprocedural I-cache optimization

### **Runtime Optimization**

### Just-in-time Compilation

Just-in-time (JIT) compilers are software dynamic translators that convert one language into another at runtime, when a segment of code (often a method) is needed.

JIT compilers can be used to support dynamic languages which are not traditionally compiled such as JavaScript or to support languages compiled into platform-independent bytecode, like Java.

Since the JIT compiler serves as a runtime environment, we can access dynamic properties of the program in order to better optimize it.

# Java class EvenOdd { public static void main(String args[]) { long evenSum=0, oddSum=0; for(int i=0)i<1000000i++) { if(i%2 == 0) { evenSum+=i; } else { oddSum=+i; } } System.out.println("Even sum: " + evenSum); System.out.println("Odd sum: " + oddSum); } }</pre>

Byteco	ode		
00 : lconst_0			
01 : lstore_1			
02 : lconst_0			
03 : 1store_3			
04 : iconst_0			
05 : istore	local.05		
07 : iload	local.05		
09 : 1dc	1		
OB : if_icmpge	pos.2A		
OE : iload	local.05		
10 : iconst_2			
11 : irem			
12 : ifne	pos.1E		
15 : lload_1			
16 : iload	local.05		
18 : i2l			
19 : ladd			
1A : lstore_1			
1B : goto	pos.24		
1E : lload_3			
1F : iload	local.05		
21 : i21			
22 : ladd			

### Bytecode 3 : istore\_3 4 : iscore\_3 4 : iscore\_3 5 : protection pos.07 5 : protection pos.07 5 : protection pos.07 6 : protection pos.07 7 : protection pos.07 8 : protection pos.07 9 : protection pos.07

A 1		
Adaptiv	e Optimization	
Consider a JIT-co	mpiler as part of a Java Virtual Machine (JVM).	
Java Bytecode is interpretation to in	a stack-oriented machine language. The JVM can use plement the virtual CPU for Java Bytecode.	
However, this inte	rpretation is slow.	
One option is to u	se JIT compilation to convert the bytecode into machine c	ode.
However, compila	tion can be slow as well.	
We have two idea 1. Apply che 2. Apply opti	s: ap yet effective optimizations mization only to regions that will benefit from it	

### **Cost-Benefit Analysis**

Let us only apply optimization O to method M if the time gained from the optimization is greater than the cost of doing the optimization. cost(M' = O(M)) < (cost(M) - cost(M'))

We need models of cost for both the optimization and the optimized method. How can we know?

For the cost of the optimization, we can base this on the complexity of the method and the average-case complexity of the algorithm  $\mathsf{O}.$ 

For the cost of the optimized method M', we must be able to predict the future.

To do this, we can look at the past.

### Profiling

We can generate a profile of method M to identify how "hot" it is. That is, how much time has been spent in the method so far by inserting instrumentation into the method code during compilation or interpretation to see how much time is spent in that code.

Execution time typically follows the Pareto Principle (the 80/20 or 90/10 rule): 90%(80%) of the time is spent in 10%(20%) of the code.

Let us only optimize those methods where we are likely to gain the most.

## **Choice of Optimizations**

Let us then define an adaptive optimization scheme. Each time a method reaches a certain level of hotness, recompile it at the next level.

For instance, a Java Adaptive Optimizer might have 4 or 5 levels:

Level 0: no optimization, potentially even interpretation Level 1: Baseline JIT, naïve code that still mimics the stack-based nature of the bytecode

Level 2: Do register allocation to remove as many of the operand stack loads and stores as possible Level 3: Apply some basic control and dataflow optimizations

Level 4: Aggressively optimize the code

This is how the Java HotSpot compiler and Jikes Research Virtual Machine work.